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# On some pseudo-differential equations and transmutation operators 

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#### Abstract

We describe some operators for solving model elliptic pseudo-differential equations in special canonical domains. It helps us to write a general solution of corresponding pseudodifferential equation in an explicit form. Moreover, knowing a general solution we can choose additional (possibly boundary) conditions to determine uniquely the solution. All considerations we give in Sobolev-Slobodetskii spaces.


## 1. Introduction

For studying pseudo-differential equations on manifolds the main difficulty is to obtain invertibility conditions for a model pseudo-differential equation in a so-called canonical domain. Since a pseudo-differential operator is defined by its symbol which depends on two variables $x$ and $\xi$, we say "model operator" if its symbol does not depend on $x$. Further, canonical domains are distinct in dependance on a type of manifold under consideration. So, for example, if we consider a compact smooth manifold without a boundary then we deal with only one canonical domain, i.e. $\mathbf{R}^{m}$. The first singularity appears if the manifold has a smooth boundary then we need to add one more canonical domain, it is a half-space $\mathbf{R}_{+}^{m}=\left\{x \in \mathbf{R}^{m}: x=\left(x^{\prime}, x_{m}\right), x_{m}>0\right\}$, because our manifold is a half-space in a neighborhood of a boundary point. The last situation was studied in details in the book [2]. But if our manifold has at least one conical point at a boundary this method of rectification of a boundary does not work, and we have next type of a singularity and next canonical domain, i.e. a cone.

This report is devoted to some studies of this case (see also [11-16]). Some other approaches one can find, for example, in $[7,8]$.

## 2. Elliptic symbols and wave factorization

We will consider the operators in the Sobolev - Slobodetskii space $H^{s}\left(\mathbf{R}^{m}\right)$ with norm

$$
\|u\|_{s}^{2}=\int_{\mathbf{R}^{m}}|\tilde{u}(\xi)|^{2}(1+|\xi|)^{2 s} d \xi
$$

where the sign " $\sim$ " over a function denotes its Fourier transform, $\tilde{u}=F u$, and introduce the following class of symbols non-depending on spatial variable $x$ : $\exists c_{1}, c_{2}>0$, such that

$$
\begin{equation*}
c_{1} \leq\left|A(\xi)(1+|\xi|)^{-\alpha}\right| \leq c_{2}, \quad \xi \in \mathbf{R}^{m} \tag{1}
\end{equation*}
$$

The number $\alpha \in \mathbf{R}$ we call the order of pseudo-differential operator $A$.
It is well-known that pseudo-differential operator with symbol $A(\xi)$ satisfying (1) is a linear bounded operator acting from $H^{s}\left(\mathbf{R}^{m}\right)$ into $H^{s-\alpha}\left(\mathbf{R}^{m}\right)$ [2].

We are interested in studying invertibility of the operators in corresponding Sobolev Slobodetskii spaces. Let $S\left(\mathbf{R}^{m}\right)$ be the Schwartz space of infinitely differentiable rapidly decreasing at infinity functions, $C$ be a sharp convex cone non-including a whole straight line. By definition, $H^{s}(C)$ consists of distributions from $H^{s}\left(\mathbf{R}^{m}\right)$ with support in $\bar{C}$. The norm in the space $H^{s}(C)$ is induced by the norm $H^{s}\left(\mathbf{R}^{m}\right)$. We consider the equation

$$
\begin{equation*}
(A u)(x)=f(x), x \in C, \tag{2}
\end{equation*}
$$

where right-hand side $f$ is chosen from the space $H_{0}^{s-\alpha}(C)$.
If $S^{\prime}\left(\mathbf{R}^{m}\right)$ is the space of distributions over the $S\left(\mathbf{R}^{m}\right)$ then $S^{\prime}(C)$ denotes the space of distributions from $S^{\prime}\left(\mathbf{R}^{m}\right)$ with support in $\bar{C}$, and $H_{0}^{s}(C)$ is the space of distributions $S^{\prime}(C)$, which admit continuation onto $H^{s}\left(\mathbf{R}^{m}\right)$. The norm in $H_{0}^{s}(C)$ is defined by

$$
\|f\|_{s}^{+}=\inf \|l f\|_{s},
$$

where infimum is chosen for all possible continuations $l f$.
Below we will consider the symbols $A(\xi)$ satisfying the condition (1).
Let us denote by $\stackrel{*}{C}$ the conjugate cone

$$
\stackrel{*}{C}=\left\{x \in \mathbf{R}^{m}: x \cdot y>0, \forall y \in C\right\} .
$$

Definition Wave factorization of symbol $A(\xi)$ with respect to the cone $C$ is called its representation in the form

$$
A(\xi)=A_{\neq}(\xi) A_{=}(\xi)
$$

where the factors $A_{\neq}(\xi), A_{=}(\xi)$ satisfy the following conditions:

1) $A_{\neq}(\xi), A_{=}(\xi)$ are defined everywhere, may be except the points $\left\{\xi \in \mathbf{R}^{m}: \xi \in \partial(\stackrel{*}{C} \cup(-\stackrel{*}{C}\right.$ )) $\}$;
2) $A_{\neq}(\xi), A_{=}(\xi)$ admit an analytical continuation into radial tube domains $T(\stackrel{*}{C}), T(-\stackrel{*}{C})$ respectively, which satisfy the estimates

$$
\begin{gathered}
\left|A_{\neq}^{ \pm 1}(\xi+i \tau)\right| \leq c_{1}(1+|\xi|+|\tau|)^{ \pm x} \\
\left|A_{\equiv}^{ \pm 1}(\xi-i \tau)\right| \leq c_{2}(1+|\xi|+|\tau|)^{ \pm(\alpha-æ)}, \forall \tau \in \stackrel{*}{C} .
\end{gathered}
$$

The number $æ$ is called the index of wave factorization.

## 3. Transmutation operators and solvability

Let the boundary surface of the cone $C$ be a function $x_{m}=\varphi\left(x^{\prime}\right)$, where $\varphi \in C^{\infty}\left(\mathbf{R}^{m-1} \backslash\{0\}\right)$ is a homogeneous function of order 1 . We will introduce the following change of variables

$$
\left\{\begin{align*}
t_{1} & =x_{1}  \tag{3}\\
t_{2} & =x_{2} \\
\cdots & \\
t_{m-1} & =x_{m-1} \\
t_{m} & =x_{m}-\varphi\left(x^{\prime}\right)
\end{align*}\right.
$$

and denote this operator by $T_{\varphi}: \mathbf{R}^{m} \rightarrow \mathbf{R}^{m}$.

Theorem The following relation holds

$$
F T_{\varphi} u=V_{\varphi} F u,
$$

where $V_{\varphi}$ is the following operator

$$
\left(V_{\varphi} \tilde{u}\right)(\xi)=\frac{1}{(2 \pi)^{m}} \int_{\mathbf{R}^{m}} \int_{\mathbf{R}^{m}} e^{i(t-y) \cdot \xi} e^{i \varphi\left(t^{\prime}\right) \xi_{m}} \tilde{u}(y) d y d t
$$

Proof. Indeed,

$$
\left(F T_{\varphi} u\right)(\xi)=\int_{\mathbf{R}^{m}} e^{i x \cdot \xi}\left(T_{\varphi} u\right)(x) d x
$$

and after change of variables (3)

$$
\left(F T_{\varphi} u\right)(\xi)=\int_{\mathbf{R}^{m}} e^{i t^{\prime} \cdot \xi^{\prime}} e^{i \varphi\left(t^{\prime}\right) \xi_{m}} e^{i t_{m} \xi_{m}} u(t) d t
$$

and taking into account

$$
u(t)=\frac{1}{(2 \pi)^{m}} \int_{\mathbf{R}^{m}} e^{-i y \cdot t} \tilde{u}(y) d y
$$

we can write

$$
\left(V_{\varphi} \tilde{u}\right)(\xi)=\frac{1}{(2 \pi)^{m}} \int_{\mathbf{R}^{m}} \int_{\mathbf{R}^{m}} e^{i(t-y) \cdot \xi} e^{i \varphi\left(t^{\prime}\right) \xi_{m}} \tilde{u}(y) d y d t
$$

Remark. This is very similar to a definition of Fourier integral operators $[4,9,10]$.
For concrete cones it is possible to calculate such operators, but before we will give the main theorem.

To formulate this theorem we will introduce a special integral operator [11]

$$
\left(G_{m} u\right)(x)=\lim _{\tau \rightarrow 0} \int_{\mathbf{R}^{m}} B(x-y+i \tau) u(y) d y, \quad \tau \in \stackrel{*}{C}
$$

where $B(z)$ is the Bochner kernel $[1,17]$

$$
B(z)=\int_{C} e^{i x \cdot z} d x, \quad z=\xi+i \tau, \quad \tau \in \stackrel{*}{C} .
$$

Theorem Let $æ-s=n+\delta$ with $n \in \mathbf{N}$ and $|\delta|<1 / 2$. A general solution of the equation (2) in Fourier image is given by the formula

$$
\begin{aligned}
& \tilde{u}(\xi)=A_{\neq}^{-1}(\xi) Q(\xi) G_{m} Q^{-1}(\xi) A_{=}^{-1}(\xi) \tilde{l} f(\xi)+ \\
& \quad+A_{\neq}^{-1}(\xi) V_{\varphi}^{-1} F\left(\sum_{k=1}^{n} c_{k}\left(x^{\prime}\right) \delta^{(k-1)}\left(x_{m}\right)\right)
\end{aligned}
$$

where $c_{k}\left(x^{\prime}\right) \in H^{s_{k}}\left(\mathbf{R}^{m-1}\right)$ are arbitrary functions, $s_{k}=s-æ+k-1 / 2, k=1,2, \ldots$, $n$, lf is an arbitrary continuation of $f$ onto $H^{s-\alpha}\left(\mathbf{R}^{m}\right), Q(\xi)$ is an arbitrary polynomial satisfying (1) for $\alpha=n$.

The a priori estimate holds

$$
\|u\|_{s} \leq C\left(\|f\|_{s-\alpha}^{+}+\left[c_{k}\right]_{s_{k}}\right),
$$

where $[\cdot]_{s_{k}}$ denotes $H^{s_{k}}\left(\mathbf{R}^{m-1}\right)$-norm.
Remark. It is easily verified that

$$
V_{\varphi}^{-1}=F T_{-\varphi}
$$

(see, for example, [15]).

## 4. Examples

We will give some calculations for the operator $V_{\varphi}$ for two concrete cones.

### 4.1. A flat case

Let us consider the case $m=2$ in details. This case admits only single sharp convex cone of the following type

$$
C_{+}^{a}=\left\{x \in \mathbf{R}^{2}: x=\left(x_{1}, x_{2}\right), x_{2}>a\left|x_{1}\right|, a>0\right\} .
$$

So we have

$$
\begin{gathered}
\left(F T_{\varphi} u\right)(\xi)=\int_{-\infty}^{+\infty} e^{i a\left|y_{1}\right| \xi_{2}} e^{i y_{1} \xi_{1}} \hat{u}\left(y_{1}, \xi_{2}\right) d y_{1}= \\
=\int_{-\infty}^{+\infty} \chi_{+}\left(y_{1}\right) e^{i a y_{1} \xi_{2}} e^{i y_{1} \xi_{1}} \hat{u}\left(y_{1}, \xi_{2}\right) d y_{1}+\int_{-\infty}^{+\infty} \chi_{-}\left(y_{1}\right) e^{-i a y_{1} \xi_{2}} e^{i y_{1} \xi_{1}} \hat{u}\left(y_{1}, \xi_{2}\right) d y_{1}= \\
=\int_{-\infty}^{+\infty} \chi_{+}\left(y_{1}\right) e^{i y_{1}\left(a \xi_{2}+\xi_{1}\right)} \hat{u}\left(y_{1}, \xi_{2}\right) d y_{1}+\int_{-\infty}^{+\infty} \chi_{-}\left(y_{1}\right) e^{-i y_{1}\left(a \xi_{2}-\xi_{1}\right.} \hat{u}\left(y_{1}, \xi_{2}\right) d y_{1},
\end{gathered}
$$

where $\hat{u}\left(y_{1}, \xi_{2}\right)$ denotes one-dimensional Fourier transform on the last variable.
The last two summands are the Fourier transforms of functions

$$
\chi_{+}\left(y_{1}\right) \hat{u}\left(y_{1}, \xi_{2}\right), \quad \chi_{+}\left(y_{1}\right) \hat{u}\left(y_{1}, \xi_{2}\right)
$$

with respect to the first variable $y_{1}$ respectively. So we can use the following properties [2] (these are Sokhotskii formulas $[3,6]$ )

$$
\begin{aligned}
& \int_{-\infty}^{+\infty} \chi_{+}(x) e^{i x \xi} u(x) d x=\frac{1}{2} \tilde{u}(\xi)+v \cdot p \cdot \frac{i}{2 \pi} \int_{-\infty}^{+\infty} \frac{\tilde{u}(\eta) d \eta}{\xi-\eta} \\
& \int_{-\infty}^{+\infty} \chi_{-}(x) e^{i x \xi} u(x) d x=\frac{1}{2} \tilde{u}(\xi)-v \cdot p \cdot \frac{i}{2 \pi} \int_{-\infty}^{+\infty} \frac{\tilde{u}(\eta) d \eta}{\xi-\eta} .
\end{aligned}
$$

Taking into account these properties we have

$$
\begin{gathered}
\left(F T_{\varphi} u\right)(\xi)=\frac{\tilde{u}\left(\xi_{1}+a \xi_{2}, \xi_{2}\right)+\tilde{u}\left(\xi_{1}-a \xi_{2}, \xi_{2}\right)}{2}+ \\
+v \cdot p \cdot \frac{i}{2 \pi} \int_{-\infty}^{+\infty} \frac{\tilde{u}\left(\eta, \xi_{2}\right) d \eta}{\xi_{1}+a \xi_{2}-\eta}-v \cdot p \cdot \frac{i}{2 \pi} \int_{-\infty}^{+\infty} \frac{\tilde{u}\left(\eta, \xi_{2}\right) d \eta}{\xi_{1}-a \xi_{2}-\eta} \equiv\left(V_{\varphi} \tilde{u}\right)(\xi) .
\end{gathered}
$$

### 4.2. A spatial case

There are a lot of sharp convex cones in a space, and we consider here $m=3$ and the following cone

$$
C_{+}^{\mathbf{a}}=\left\{x \in \mathbf{R}^{3}: x=\left(x_{1}, x_{2}, x_{3}\right), x_{3}>a_{1}\left|x_{1}\right|+a_{2}\left|x_{2}\right|, a_{1}, a_{2}>0\right\}
$$

For calculating the operator $V_{\varphi}$ we evaluate

$$
\begin{gathered}
\int_{\mathbf{R}^{2}} e^{i\left(a_{1}\left|y_{1}\right|+a_{2}\left|y_{2}\right|\right) \xi_{3}} e^{i\left(y_{1} \xi_{1}+y_{2} \xi_{2}\right)} \hat{u}\left(y_{1}, y_{2}, \xi_{3}\right) d y_{1} d y_{2}= \\
=\int_{-\infty}^{+\infty} e^{i\left(a_{1}\left|y_{1}\right| \xi_{3}+y_{1} \xi_{1}\right)}\left(\int_{-\infty}^{+\infty} e^{i\left(a_{2}\left|y_{2}\right| \xi_{3}+y_{2} \xi_{2}\right)} \hat{u}\left(y_{1}, y_{2}, \xi_{3}\right) d y_{2} d y_{1}=\right. \\
=\int_{-\infty}^{+\infty} e^{i\left(a_{1}\left|y_{1}\right| \xi_{3}+y_{1} \xi_{1}\right)}\left(\frac{\hat{\hat{u}}\left(y_{1}, \xi_{2}-a_{2} \xi_{3}, \xi_{3}\right)+\hat{\hat{u}}\left(y_{1}, \xi_{2}+a_{2} \xi_{3}, \xi_{3}\right)}{2}+\right. \\
\left.+v \cdot p \cdot \frac{i}{2 \pi} \int_{-\infty}^{+\infty} \frac{\hat{\hat{u}}\left(y_{1}, \eta, \xi_{3}\right) d \eta}{\xi_{2}+a_{2} \xi_{3}-\eta}-v \cdot p \cdot \frac{i}{2 \pi} \int_{-\infty}^{+\infty} \frac{\hat{\hat{u}}\left(y_{1}, \eta, \xi_{3}\right) d \eta}{\xi_{2}-a_{2} \xi_{3}-\eta}\right) d y_{1}
\end{gathered}
$$

where $\hat{\hat{u}}$ denotes the Fourier transform with respect to the two last variables.
Let us denote

$$
\begin{aligned}
v_{1}(\xi)= & \frac{1}{2} \int_{-\infty}^{+\infty} e^{i\left(a_{1}\left|y_{1}\right| \xi_{3}+y_{1} \xi_{1}\right)} \hat{\hat{u}}\left(y_{1}, \xi_{2}-a_{2} \xi_{3}, \xi_{3}\right) d y_{1} \\
v_{2}(\xi)= & \frac{1}{2} \int_{-\infty}^{+\infty} e^{i\left(a_{1}\left|y_{1}\right| \xi_{3}+y_{1} \xi_{1}\right)} \hat{\hat{u}}\left(y_{1}, \xi_{2}+a_{2} \xi_{3}, \xi_{3}\right) d y_{1} \\
w_{1}(\xi)= & \int_{-\infty}^{+\infty} e^{i\left(a_{1}\left|y_{1}\right| \xi_{3}+y_{1} \xi_{1}\right)}\left(S_{2} \hat{\hat{u}}\right)\left(y_{1}, \xi_{2}+a_{2} \xi_{3}, \xi_{3}\right) d y_{1} \\
w_{2}(\xi)= & \int_{-\infty}^{+\infty} e^{i\left(a_{1}\left|y_{1}\right| \xi_{3}+y_{1} \xi_{1}\right)}\left(S_{2} \hat{\hat{u}}\right)\left(y_{1}, \xi_{2}-a_{2} \xi_{3}, \xi_{3}\right) d y_{1}
\end{aligned}
$$

where

$$
\left(S_{2} u\right)\left(\xi_{1}, \xi_{2}, \xi_{3}\right)=v \cdot p \frac{i}{2 \pi} \int_{-\infty}^{+\infty} \frac{u\left(\xi_{1}, \eta, \xi_{3}\right) d \eta}{\xi_{2}-\eta}
$$

Further, taking into account the fact $\hat{\hat{u}} \equiv \tilde{u}$ and the relation

$$
\left(S_{1} u\right)\left(\xi_{1}, \xi_{2}, \xi_{3}\right)=v \cdot p \frac{i}{2 \pi} \int_{-\infty}^{+\infty} \frac{u\left(\tau, \xi_{2}, \xi_{3}\right) d \tau}{\xi_{1}-\tau}
$$

we obtain

$$
\int_{\mathbf{R}^{2}} e^{i\left(a_{1}\left|y_{1}\right|+a_{2}\left|y_{2}\right|\right) \xi_{3}} e^{i\left(y_{1} \xi_{1}+y_{2} \xi_{2}\right)} \hat{u}\left(y_{1}, y_{2}, \xi_{3}\right) d y_{1} d y_{2}=
$$

$$
\begin{gathered}
=\frac{\tilde{u}\left(\xi_{1}-a_{1} \xi_{3}, \xi_{2}-a_{2} \xi_{3}, \xi_{3}\right)+\tilde{u}\left(\xi_{1}+a_{1} \xi_{3}, \xi_{2}-a_{2} \xi_{3}, \xi_{3}\right)}{4}+ \\
+\frac{1}{2}\left(S_{1} \tilde{u}\right)\left(\xi_{1}+a_{1} \xi_{3}, \xi_{2}-a_{2} \xi_{3}, \xi_{3}\right)-\frac{1}{2}\left(S_{1} \tilde{u}\right)\left(\xi_{1}-a_{1} \xi_{3}, \xi_{2}-a_{2} \xi_{3}, \xi_{3}\right)+ \\
\quad+\frac{\tilde{u}\left(\xi_{1}-a_{1} \xi_{3}, \xi_{2}+a_{2} \xi_{3}, \xi_{3}\right)+\tilde{u}\left(\xi_{1}+a_{1} \xi_{3}, \xi_{2}+a_{2} \xi_{3}, \xi_{3}\right)}{4}+ \\
+\frac{1}{2}\left(S_{1} \tilde{u}\right)\left(\xi_{1}+a_{1} \xi_{3}, \xi_{2}+a_{2} \xi_{3}, \xi_{3}\right)-\frac{1}{2}\left(S_{1} \tilde{u}\right)\left(\xi_{1}-a_{1} \xi_{3}, \xi_{2}+a_{2} \xi_{3}, \xi_{3}\right)+ \\
+\frac{\left(S_{2} \tilde{u}\right)\left(\xi_{1}-a_{1} \xi_{3}, \xi_{2}+a_{2} \xi_{3}, \xi_{3}\right)+\left(S_{2} \tilde{u}\right)\left(\xi_{1}+a_{1} \xi_{3}, \xi_{2}+a_{2} \xi_{3}, \xi_{3}\right)}{2}+ \\
+\left(S_{1} S_{2} \tilde{u}\right)\left(\xi_{1}+a_{1} \xi_{3}, \xi_{2}+a_{2} \xi_{3}, \xi_{3}\right)-\left(S_{1} S_{2} \tilde{u}\right)\left(\xi_{1}-a_{1} \xi_{3}, \xi_{2}+a_{2} \xi_{3}, \xi_{3}\right)- \\
-\frac{\left(S_{2} \tilde{u}\right)\left(\xi_{1}-a_{1} \xi_{3}, \xi_{2}-a_{2} \xi_{3}, \xi_{3}\right)+\left(S_{2} \tilde{u}\right)\left(\xi_{1}+a_{1} \xi_{3}, \xi_{2}-a_{2} \xi_{3}, \xi_{3}\right)}{2}- \\
-\left(S_{1} S_{2} \tilde{u}\right)\left(\xi_{1}+a_{1} \xi_{3}, \xi_{2}-a_{2} \xi_{3}, \xi_{3}\right)+\left(S_{1} S_{2} \tilde{u}\right)\left(\xi_{1}-a_{1} \xi_{3}, \xi_{2}-a_{2} \xi_{3}, \xi_{3}\right) .
\end{gathered}
$$

Thus, we see that the operator $V_{\varphi}$ is composed from operators $S_{1}, S_{2}$ and certain change of variables.

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