# SPECTRO-POLARIMETRIC IMAGING REVEALS HELICAL MAGNETIC FIELDS IN SOLAR PROMINENCE FEET 

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#### Abstract

Solar prominences are clouds of cool plasma levitating above the solar surface and insulated from the milliondegree corona by magnetic fields. They form in regions of complex magnetic topology, characterized by nonpotential fields, which can evolve abruptly, disintegrating the prominence and ejecting magnetized material into the heliosphere. However, their physics is not yet fully understood because mapping such complex magnetic configurations and their evolution is extremely challenging, and must often be guessed by proxy from photometric observations. Using state-of-the-art spectro-polarimetric data, we reconstruct the structure of the magnetic field in a prominence. We find that prominence feet harbor helical magnetic fields connecting the prominence to the solar surface below.


Key words: polarization - Sun: chromosphere - Sun: corona - Sun: magnetic fields
Supporting material: animations

## 1. THE EMPIRICAL STUDY OF MAGNETIC FIELDS IN SOLAR PROMINENCES

Solar prominences are seen as bright translucent clouds at $\sim 10 \mathrm{Mm}$ over the solar limb because they mainly scatter light from the underlying disk. When seen on the solar disk, they appear as dark, long filamentary structures, hence called filaments. The main body of the filament (spine) often has shorter side-wards extensions (filament barbs) which, when seen at the limb, give the impression of extending from the spine to the photosphere below (prominence feet; Mackay et al. 2010).

It has long been clear that a magnetic field supports the dense material of prominences against gravity and prevents them from dissipating into the faint, extremely hot corona. Local dips on magnetic field lines can support the plasma, and could be induced by the dense, heavy prominence plasma itself (Kippenhahn \& Schlüter 1957), or they can exist in forcefree (Antiochos et al. 1994; Aulanier \& Demoulin 1998) or stochastic magnetic fields (van Ballegooijen \& Cranmer 2010). Yet, all these theoretical claims must be constrained by the empirical determination of magnetic fields in prominences.
In the Sun, and in any astrophysical plasma in general, we are not able to directly measure these fields, but we are obliged to infer them from the light they emit. Spectro-polarimetry, the measurement of the polarized spectrum of light allows us to recover quantitative information on the magnetic field vector. The polarization state of observed light is compatible with the intrinsic (broken) symmetries of the emitting plasma, in particular, with the presence of a magnetic field. Thus, for example, the emission by an isotropic (and therefore unmagnetized) medium is unpolarized. Polarized emission along a magnetic field is circularly polarized while, normally to the field, it is linearly polarized, as in the longitudinal or transversal Zeeman effects, respectively (e.g., Landi Degl'Innocenti \& Landolfi 2004). If light is scattered, additional
symmetries are broken and the dependencies of polarization are more involved. In solar prominences and filaments, spectral lines are polarized by scattering and the Zeeman effect, and futher modified by the Hanle effect (Tandberg-Hanssen 1995; Landi Degl'Innocenti \& Landolfi 2004), providing direct information on the magnetic field vector.
Many studies have observed prominences with the aim to determine magnetic fields. Some maps of the magnetic field vector in quiescent prominences show horizontal magnetic fields of $\sim 10-20 \mathrm{G}$ (Casini et al. 2003; Orozco Suárez et al. 2014), in agreement with results obtained in the 1970's and 1980's from observations with limited spatial resolution (Sahal-Brechot et al. 1977; Leroy 1989). In contrast, vertical fields have also been diagnosed in prominences (Merenda \& Trujillo Bueno 2006). Considering prominence feet, the observation of vertical velocities in these structures suggests vertical fields directly connecting the spine with the photosphere (Zirker et al. 1998). Also, from observations of photospheric magnetic fields (not the prominence itself), the barbs are interpreted as a series of local horizontal dips sustaining plasma at different heights (López Ariste et al. 2006).
In light of these results it is clear that, from an observational point of view, the precise topology of magnetic fields in prominences is still a matter of debate. The main reasons are that (1) measuring the polarized spectrum of solar prominences is an observational challenge, and (2) the inference of the magnetic field vector in the Hanle regime is subject to potential ambiguities. In this paper, we reconstruct the topology of the feet of a quiescent prominence from spectro-polarimetric data at the He i 1083.0 nm line. We study the possible solutions to the inverse problem and, in contrast to previous results, we discard some of them using a physical constraint. We also propose an analytical method to be used to find the multiple
solutions in the case of Hanle diagnostics in prominences and write the explicit equations in the Appendix.

## 2. NEAR-INFRARED SPECTRO-POLARIMETRY AND MULTIWAVELENGTH IMAGING

On 2011 April 24 (10:00-13:00 UT), we performed four consecutive spectro-polarimetric scans of a quiescent prominence (located at 90 E 42 S ) focusing at the 1083.0 nm multiplet using the Tenerife Infrared Polarimeter (Collados 1999) at the German Vacuum Tower Telescope in the Observatorio del Teide. We integrated 30 s per scan step to reach a polarimetric sensitivity of $7 \times 10^{-4}$ times the maximum intensity. Each scan of the prominenece took around 30 minutes. This data set constitutes a unique time series of high polarimetric sensitivity and unprecedented spatial resolution ( $\sim 470 \mathrm{~km}$ on the Sun) of a prominence. We applied standard reduction procedures to the raw spectra (bias and flatfield correction, and polarization demodulation) to obtain maps of the four Stokes parameters I, Q, U, and V (Figures 1(c)-(f)). The slit was always kept across the solar limb (horizontal direction in the images), which allowed us to correct for seeing-induced cross-talk and stray light (Martínez González et al. 2012). The seeing conditions were excellent, the adaptive optics system often reaching an apparent mirror diameter of 20 cm . This made the applied seeing-induced corrections very small, i.e., close to the limb, where the effects of seeing are expected to be the largest, the average corrections applied were $5 \times 10^{-5}$ times the maximum intensity.

Simultaneous images were taken with a narrow-band Lyot filter centered at the core of the $\mathrm{H}_{\alpha}$ line with a cadence of 1 s . These images were treated with blind deconvolution techniques (van Noort et al. 2005) to resolve very fine spatial details of the temporal evolution of the prominence (Figure 1(a) and the online version of the $\mathrm{H}_{\alpha}$ movie). Further context was provided by imaging in the coronal line of Fe IX at 17.1 nm (Figure 1(b)) observed with the Atmospheric Imaging Assembly (AIA; Lemen et al. 2012) instrument on board the Solar Dynamics Observatory (Pesnell et al. 2012).

In this paper, we focus on the study of the third scan because of the double-helix appearence of the prominence feet. Figure 1 displays the multiwavelength intensity, and polarimetric imaging of the observed prominence. Both in the He i 1083.0 nm scan and $\mathrm{H}_{\alpha}$ intensity images, one of the two prominence feet (f2 from Figure 1(f)) shows a clear doublehelix structure formed by two fibrils. A more compact, twisted helical structure can also be guessed in foot f1. The two prominence feet correspond to vertical, dark (absorption) structures observed at 17.1 nm that resemble the so-called solar tornadoes (Pettit 1932; Su et al. 2012; Wedemeyer 2013). They were observable in the AIA data for almost three more days, and on April 26 (23:38 UT), they suddenly erupted, showing a clear helical shape. Interestingly, the foot f 2 presents opposite polarities of the Stokes $V$ parameter at both sides of one fibril (f2a). This means that the magnetic field has reversed polarities along the line of sight (LOS) at both sides of this fibril. Moreover, when subtracting the average circular polarization (i.e., the mean longitudinal magnetic field) to the other fibril of feet f 2 (panel f2b) and to the other feet (f1), we find similar patterns.

## 3. INFERENCE OF THE MAGNETIC AND DYNAMIC STRUCTURE OF THE PROMINENCE FEET

We analyze the spectro-polarimetric data using the numerical code Hanle Zeeman Light (HaZeL; Asensio Ramos et al. 2008) to recover the full magnetic field vector and the thermodynamical properties of the plasma. Facing an inverse problem with observational data and a large number of dimensions is always ill-posed. A classical inversion code such as HaZeL retrieves one atmospheric model that fits the observed profiles, though others may exist. In our case, the number of these ambiguous solutions depend on the regime of the magnetic field and, more importantly, on the scattering geometry. Our approach is to find compatible solutions of the same inverse problem in each pixel and then select the global scenario physically compatible with the context. This procedure step is essential to reconstruct the global topology of the magnetic field in the prominence.

### 3.1. Determination of the Scattering Geometry

The angle of the emitting atom in the local vertical (LV) (or the observed strcuture if we assume it in the same plane) with respect to the LOS (the scattering angle $\theta$ ) is a very important parameter to correctly infer the magnetic field vector from spectro-polarimetric signals generated from scattering processes. In order to determine it, we used the images of the AIA at 17.1 nm in which we identified the feet of our observed prominence as two dark (absorption) vertical filaments (Figure 1(b)). We followed these filaments as they entered onto the disk and detected their positions (as a projection onto the plane of the sky). We measure the projected distance of the filaments to the limb $d$ over time $t$ and fit it with the approximate expression

$$
\begin{equation*}
\frac{d}{R} \sim \frac{1}{2} \omega^{2}\left(t-t_{\mathrm{limb}}\right)^{2} \tag{1}
\end{equation*}
$$

inferring the value of $t_{\text {limb }}$, the time at which the prominence feet were at the limb. The symbol $R$ is the radius of the parallel at latitude $l=42^{\circ}$, and $\omega=0.55^{\circ} \mathrm{h}^{-1}$ is the solar angular velocity at that latitude. The distance $d$ was obtained as the length of the horizontal line from the foot to the limb, which is a good approximation close to the limb. The inferred scattering angle (the angle between the LOS and the LV) is approximately given by

$$
\begin{equation*}
\theta \sim-\cos l(2 d / R)_{\mathrm{obs}}^{1 / 2} \tag{2}
\end{equation*}
$$

The distance $(d / R)_{\text {obs }}$ obtained by substituting $t=t_{\mathrm{obs}}$, i.e., the time of the observations, in Equation (1). After this procedure, we obtain that the spectro-polarimetric scan was taken at a scattering geometry of $\theta=98^{\circ}$, i.e., while the prominence was slightly behind the limb.

### 3.2. Determination of Multiple Solutions

We follow a two-step inversion scheme to obtain a robust convergence of the code. Since the magnetic field is of second order to the intensity profile, we first use the intensity profile alone to infer the thermodynamical quantities. On a second step, we fix the thermodynamical parameters and find the magnetic field vector using the information of the polarization profiles.

As stated before, this may not be the unique solution to the problem. In order to capture all possible solutions we follow, again, a two-step procedure. First, we sample the space of parameters with approximate (though appropriate) analytical


Figure 1. (a) Prominence seen at the core of $\mathrm{H}_{\alpha}$. This snapshot was recorded half way through the spectropolarimetric scan. (b) Prominence as seen at 17.1 nm . This snapshot was recorded 10 h after the spectro-polarimetric scan, when the pillars of the tornadoes were more prominent (no need for sharp-marsking filter) than at the time of the observations. (c) Reconstructed intensity map at the core of the He i 1083.0 nm line. (d) and (e) Maps of the amplitude of linear polarization Stokes $Q$ \& $U$. The reference direction for positive Stokes $Q$ is parallel to the limb. (f) Map of the amplitude of circular polarization Stokes $V$. Insets show detailed views of the circular polarization in both feet. Insets f1-f2b: stokes $V$ in the region after subtracting the average value (f1 and f2b).
(An animation of this figure is available.)
expressions. Finally, we use these analytical solutions as initial guesses for a second HaZeL inversion. This will allow us to refine the solutions in the general unsaturated regime to overcome the approximations we have made.

In the case of an optically thin plasma, a normal Zeeman triplet, and a magnetic field in the saturated Hanle effect regime -when the Larmor frequency is much larger than the inverse of the characteristic time for scattering-the geometric dependencies of polarization are simply expressed through the Stokes parameters as (Casini et al. 2005)

$$
\begin{align*}
& Q \propto\left(3 \cos ^{2} \theta_{B}-1\right) \sin ^{2} \Theta_{B} \cos 2 \Phi_{B} \\
& U \propto\left(3 \cos ^{2} \theta_{B}-1\right) \sin ^{2} \Theta_{B} \sin 2 \Phi_{B} \\
& V \propto \cos \Theta_{B} \tag{3}
\end{align*}
$$

showing a dependence on the inclination $\Theta_{B}$ and azimuth $\Phi_{B}$ of
the magnetic field with respect to the LOS, like in the Zeeman effect, and an additional dependence on the geometry of the scattering event through the inclination $\theta_{B}$ of the magnetic field with respect to the LV . The linearly polarized components (Stokes $Q$ and $U$ ) are dominated by scattering polarization and the Hanle effect, while the circularly polarized component (Stokes $V$ ) is generated by the longitudinal Zeeman effect, and defines the polarity of the magnetic field along the LOS (Landi Degl'Innocenti \& Landolfi 2004).

Equation (3) shows a dependence of polarization on $\Theta_{B}$ and $\Phi_{B}$ that yield the well-known $180^{\circ}$-ambiguity for $\Phi_{B}$ of classical Zeeman diagnostics. The additional dependence on $\theta_{B}$, characteristic of scattering processes, may yield two additional ambiguous solutions for the magnetic field (Casini et al. 2005). The He i 1083.0 nm line often forms close to the saturation regime described by Equation 3 and all (up to four) ambiguous
field configurations can be determined analytically (see the Appendix; see also Judge 2007).

In order to have an idea of the potential multiple solutions we face, we have represented in Figure 4 the so-called Hanle diagram: the amplitude of Stokes $Q$ and $U$ in terms of the inclination $\left(\theta_{B}\right)$ and azimuth $\left(\phi_{B}\right)$ of the magnetic field in the LV . The diagram is computed for a point at $15^{\prime \prime}$ above the solar limb (middle-upper parts of the observed prominence feet). We have assumed the saturation regime (in particular a field strength of 30 G ), and the scattering angle determined by our observations $\left(98^{\circ}\right)$. The zero inclination is defined as a field in the LV, and the zero azimuth is defined in the LOS, being $\phi_{B}=180^{\circ}$ a field directed away from the observer.

The more vertical fields $\left(\theta_{B} \leqslant 35^{\circ}\right.$ and $\left.\theta_{B} \geqslant 145^{\circ}\right)$ have four possible solutions irrespective of the azimuth value: two of them (the ones represented by filled and empty circles) are not ambiguous if circular polarization is observed, since it provides the sign of the longitudinal component of the magnetic field. The other two solutions have opposite polarities of the field in the LV. Fields with inclinations between $35^{\circ}$ and $145^{\circ}$ have eight possible solutions: a more vertical inclination with the four solutions stated above and another four solutions with more inclined fields. In the case of our observations, the sensitivity of circular polarization allows us to constrain the azimuth range, and hence only four ambiguous solutions need to be determined. The polarity of the field (in the LV) cannot be determined. However, as we will see, this ambiguity is unimportant for the purposes of this paper.

### 3.3. The Helical Magnetic Field

The ambiguities apply at each pixel of our observations. However, we assume that there are no tangential discontinuities or shocks and hence the magnetic field in the prominence draw continuous lines. We reconstructed four global topologies of the magnetic field which could be grouped into two broad categories: one with fields inclined by $\theta_{B} \sim 30^{\circ}, 150^{\circ}$, and another one with more inclined fields $\left(\theta_{B} \sim 90^{\circ}\right)$. In both cases, the projection of the field onto the plane of the sky is at an angle with the axis of each fibril that form the prominence feet. The fibril f2a (displayed in Figure 1) shows an LOS polarity reversal at opposite sides of its axis. Similar LOS polarity inversions appear across the axes of the other fibrils when the average value of Stokes V in the region, corresponding to the mean LOS component of the magnetic field, is subtracted (Figures 1(f1) and (f2b)). Put together, this points to a helical global topology in both families of solutions, with the more horizontal configurations showing a more twisted field.

In order to disambiguate the problem, we introduce a physical constraint through a stability analysis. According to the Kruskal-Shafranov criterion (Hood \& Priest 1979) a kink instability develops when the amount of magnetic twist exceeds a critical value, so that a structure is stable if

$$
\begin{equation*}
\frac{2 \pi r}{L} \frac{B_{z}}{B_{\theta}} \geqslant 1 \tag{4}
\end{equation*}
$$

where $r$ and $L$ are the radius and the length of the fibril, respectively, and $B_{z}$ and $B_{\theta}$ are the vertical and azimuthal components of the magnetic field, respectively. Estimating $r=1.7 \mathrm{Mm}$ and $L=11.6 \mathrm{Mm}$ for our prominence, the stability criterion yields 0.09 for the solution with the fields around $90^{\circ}$ and 1.28 for the fields with inclinations of $30^{\circ}$ and $150^{\circ}$.


Figure 2. (a) Inferred magnetic field topology of the prominence feet. Direction of the field projected onto the plane of the sky (short lines) overplotted to the intensity of the $\mathrm{He}_{\text {I }} 1083.0 \mathrm{~nm}$ line and magnetic field strength (b). Short-dashed black lines in panel (a) trace the axes of the fibrils in the two feet. In the sketches below, blue arrows represent the actual inferred field vector in the f2a fibril. Note the opposite polarities of the magnetic field in both sides of the local vertical. This, and the relative inclination of the projected field with respect to the fibrils imply a helical field (red lines).

Figure 2 shows the magnetic field strength and topology of the magnetic field. The magnetic field strength has very similar values throughout all families of solutions. In most of the prominence the magnetic field strength is below 20 G , but shows filamentary structures, parallel to the helix structure, of higher field strength ( $\sim 60 \mathrm{G}$; Figure 2(b)). The projection of the field onto the plane of the sky is always roughly perpendicular to the solar limb, and at an angle $\left(\sim 30^{\circ}-50^{\circ}\right)$ with the axis of the fibrils that form the prominence feet (Figure 2(a)). All fibrils present magnetic field polarity reversals at both sides of their axis. This implies a helical field along the fibrils with the axis in the plane of the sky in f2a (since the average longitudinal magnetic field is close to zero), and slightly tilted relative to the LV in the other fibrils (since polarity reversals are only seen when the mean longitudinal magnetic field is subtracted). The helical magnetic fields of the two fibrils are interlaced to form a double-helix that constitutes one foot of the prominence (see Figure 3 and the online movie of the artistic representation of the field topology). The feet magnetically connect the spine with lower layers, in contrast to


Figure 3. Artistic representation of the three-dimensional magnetic field in the observed. In (a) blue and red lines represent arbitrary, recovered field lines in the prominence feet; gray lines follow field lines in the spine according to overall models for prominence structure and are only drawn as context (i.e., the twist of field lines does not represent reality). Background image: intensity in the He i 1083.0 nm line. (b) and (c) Side views (see the online movie of the three-dimensional reconstruction).
(An animation of this figure is available.)
previous works suggesting that feet are just a collection of dips at different heights López Ariste et al. (2006).

### 3.4. Motions of the Prominence Material

The intensity profiles of the $\mathrm{He}_{\mathrm{r}}$ line carry information on the LOS velocity, opacity, temperature, and density of the structure. We recover all these parameters along with the magnetic topology using the HaZeL code. They have the same values for all families of solutions of the magnetic field.

Figure 5(a) shows the inferred LOS velocities. Interestingly, they have opposite signs at both sides of both feet of the prominence ( f 1 and f2), with values up to $2 \mathrm{~km} \mathrm{~s}^{-1}$ (similar values as Orozco Suárez et al. 2012). Assuming that the neutral atoms of He still trace the field lines, this pattern of velocities could be a natural consequence if the prominence material is flowing along the inferred double-helix structure of the prominence feet. Note that f 1 has a positive-negative Doppler pattern at lower heights, while it has a negative-positive one higher in the feet, as we would expect for a more compact double-helix, which implies a larger twist.

If the material is flowing along the helical field lines of the fibrils of each feet, a Doppler pattern similar to that of large scales should be observed at smaller scales. The upper parts of f2a show a positive-negative pattern. The rest of the fibrils have


Figure 4. Hanle effect diagram for the He I 1083.0 nm line computed with the HaZeL code assuming a $98^{\circ}$ scattering geometry and the saturation regime $(B=30 \mathrm{G})$. The inclination $\left(\theta_{B}\right)$ and azimuth $\left(\phi_{B}\right)$ are referred to the LV. The $\chi_{B}=0$ corresponds to the line of sight, and $\chi_{B}=0$ for a radial vector away from the Sun (see Asensio Ramos et al. 2008). The solid lines represent the curves at constant inclination. The Hanle diagram for the range of inclinations between $90^{\circ}$ and $180^{\circ}$ is the same but with a reversed color palette. The orange dots represent the observed polarization amplitudes. All the observed points have ambiguous vertical and horizontal solutions. However, note that the sign of the circular polarization is only compatible with one of the solutions represented by filled or empty dots.


Figure 5. (a) LOS velocity field from the inversion of the He I 1083.0 nm observations with intensity contours (white lines) overplotted for reference. (b) Space-time variations of $\mathrm{H}_{\alpha}$ intensity for an artificial slit at 5.8 Mm , parallel to the limb across the helical structure (gray line). Brackets mark the time interval during the scan of f2. Dotted yellow lines trace the periodic movement of the two fibrils in the double-helix.
a continuous increase of the Doppler velocity as we move from left to right across the structure. This could be interpreted as a negative-positive pattern if the fibrils are not at a $90^{\circ}$ scattering geometry, which is very likely.

The two fibrils of $f 2$ exhibit a periodic motion in the $\mathrm{H}_{\alpha}$ spacetime diagram, with a period of $\sim 60$ minutes (Figure 5(b)), consistent with the periods reported in Su et al. (2012) for solar tornadoes. Assuming that the change in $\mathrm{H}_{\alpha}$ brightness is only due to plasma movements, the observed periodic motion could also be interpreted in terms of plasma flowing along helical field lines. Rotation of the magnetic structure is very unlikely since the observed $\sim 50$ minutes period would imply a full turn of the magnetic field in less than one hour. This will considerably increase the twist of the structure and will soon make it unstable under magnetohydrodynamical instabilities (easily within a day). The plane-of-the-sky periodic motions show maximum tangential velocities of $\sim 9 \mathrm{~km} \mathrm{~s}^{-1}$, which are far larger than the ones inferred from the Doppler effect in the $\mathrm{He}_{\text {I }}$ line. We must be careful to directly relate those two velocities since Doppler measurements are generated only by plasma motions while changes in $\mathrm{H}_{\alpha}$ brightness cannot only be assigned to plasma movements but to changes in the thermal conditions.

## 4. DISCUSSION

The feet of the observed prominence harbor helical magnetic fields. After assuming a simple stability criterion, we have a preference for the more vertical solution and conclude that the
magnetic fields in prominence feet connect the spine with the underlying atmosphere. These results are in contrast to the scenario in which these structures are formed by a series of local horizontal dips that sustain the plasma at different heights (Aulanier et al. 1999; López Ariste et al. 2006). Assuming a uniformly twisted straight cylinder, the magnetic field displays a twist (number of turns over its length $L$ ) of 1.32 at each fibril. We speculate that the connectivity of the prominence spine, with a well-defined helicity, and the photospheric magnetic field below, with a fluctuating topology, may naturally yield the kind of helical structures we find.

The $\mathrm{He}_{\text {I }}$ Doppler velocities display opposite velocities along the LOS at both sides of prominence feet. The $\mathrm{H}_{\alpha}$ intensity displays periodic motions in the plane-of-the-sky. Using only the Doppler velocities or the plane-of-the-sky motions alone do not allow to reach any conclusion on the plasma motions and can lead to controversies in the literature (e.g., Orozco Suárez et al. 2012; Panasenco et al. 2014). If we put the $\mathrm{He}_{\text {I }}$ and the $\mathrm{H}_{\alpha}$ information together, we could interpret these observations as the material of the prominence flowing along helical field lines. However, the LOS Doppler velocities inferred from the $\mathrm{He}_{\text {I }}$ line and the tangential velocities expected for the observed period of the $\mathrm{H}_{\alpha}$ images do not match. It could be that neutral H and He clouds have different thermodynamical properties or it could be that the changes in the $\mathrm{H}_{\alpha}$ brightness have an important contribution from changing thermal conditions, but we need more data to really understand this issue.

The prominence remains stable for several days, and we think that the magnetic topology of the prominence feet
reported in this paper plays a fundamental role in the stability of the prominence as a whole.

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## APPENDIX A AMBIGUITIES IN THE HANLE EFFECT IN THE SATURATION REGIME

In the saturation regime of the Hanle effect, Stokes $Q$ and $U$ are insensitive to the field strength, but are sensitive to the geometry of the field. For a two-level atom with a $J_{\text {up }}=0 \rightarrow J_{\text {low }}=1$ transition, the optically thin limit, and the saturation regime for the Hanle effect, the linear polarization can be written as.

$$
\begin{align*}
Q & =\frac{q}{2}\left(3 \cos ^{2} \theta_{B}-1\right) \sin ^{2} \Theta_{B} \cos 2 \Phi_{B} \\
U & =\frac{q}{2}\left(3 \cos ^{2} \theta_{B}-1\right) \sin ^{2} \Theta_{B} \sin 2 \Phi_{B} \tag{A.1}
\end{align*}
$$

The inclination and azimuth of the magnetic field in the LV are represented by the symbols $\Theta_{B}$ and $\Phi_{B}$, respectively. In the LOS, the inclination and azimuth are displayed as $\theta_{B}$ and $\phi_{B}$. These equations are formally the same irrespective of the scattering angle $\theta$. The dependence on the scattering geometry is implicit in the amplitude in the abscence of a magnetic field $q$.

The coordinates of the magnetic field vector $\boldsymbol{B}$ in the reference system of the vertical and the reference system of the LOS are

$$
\begin{align*}
\boldsymbol{B}= & B\left(\sin \theta_{B} \cos \phi_{B} \boldsymbol{i}+\sin \theta_{B} \sin \phi_{B} \boldsymbol{j}+\cos \theta_{B} \boldsymbol{k}\right) \\
\boldsymbol{B}= & B\left(\sin \Theta_{B} \cos \Phi_{B} \boldsymbol{i}^{\prime}+\sin \Theta_{B} \sin \Phi_{B} \boldsymbol{j}^{\prime}\right. \\
& \left.+\cos \Theta_{B} \boldsymbol{k}^{\prime}\right) \tag{A.2}
\end{align*}
$$

where the unit vectors are related by a simple rotation:

$$
\begin{align*}
\boldsymbol{i}^{\prime} & =\cos \theta \boldsymbol{i}-\sin \theta \boldsymbol{k} \\
\boldsymbol{k}^{\prime} & =\sin \theta \boldsymbol{i}+\cos \theta \boldsymbol{k} \tag{A.3}
\end{align*}
$$

Given that the magnetic field vector must be the same in both
reference systems, we find that the following relations apply.

$$
\begin{aligned}
\sin \theta_{B} \cos \phi_{B} & =\sin \Theta_{B} \cos \Phi_{B} \cos \theta+\cos \Theta_{B}+\sin \theta \\
\sin \theta_{B} \sin \phi_{B} & =\sin \Theta_{B} \sin \Phi_{B} \\
\cos \theta_{B} & =\cos \Theta_{B} \cos \theta-\sin \Theta_{B} \cos \Phi_{B} \sin \theta . ~(\text { A.4) }
\end{aligned}
$$

Solving the previous three equations in the two directions, we find the following transformations between the angles in the vertical reference system and the LOS reference system.

$$
\begin{align*}
\cos \Theta_{B} & =\cos \theta \cos \theta_{B}+\sin \theta \sin \theta_{B} \cos \phi_{B} \\
\sin \Theta_{B} & =+\sqrt{1-\cos ^{2} \Theta_{B}} \\
\cos \Phi_{B} & =\frac{\cos \theta \sin \theta_{B} \cos \phi_{B}-\cos \theta_{B} \sin \theta}{\sin \Theta_{B}} \\
\sin \Phi_{B} & =\frac{\sin \theta_{B} \sin \phi_{B}}{\sin \Theta_{B}} \tag{A.5}
\end{align*}
$$

and

$$
\begin{align*}
\cos \theta_{B} & =\cos \theta \cos \Theta_{B}-\sin \theta \sin \Theta_{B} \cos \Phi_{B} \\
\sin \theta_{B} & =+\sqrt{1-\cos ^{2} \theta_{B}} \\
\cos \phi_{B} & =\frac{\cos \theta \sin \Theta_{B} \cos \Phi_{B}+\cos \Theta_{B} \sin \theta}{\sin \theta_{B}} \\
\sin \phi_{B} & =\frac{\sin \Theta_{B} \sin \Phi_{B}}{\sin \theta_{B}} \tag{A.6}
\end{align*}
$$

Note that, since $\Theta_{B} \in[0, \pi]$, we can safely use the square root and take the positive value. In order to transform from one reference system to the other, we can compute the inclination easily by inverting the sinus or the cosinus. However, the situation is different for the azimuth, because the range of variation is $[-\pi, \pi]$. Therefore, one has to compute the cosinus and the sinus separately and the decide which is the correct quadrant for the angle in terms of the signs of both quantities.

Four multiple solutions can exist for the Stokes $Q$ and $U$ parameters. The idea is that $\Phi_{B}$ can be modified and still obtain the same $Q$ and $U$ by properly adjusting the value of $\Theta_{B}$. It is clear that, given that the term that can be used to compensate for the change in the azimuth on the LOS reference system is the same for Stokes $Q$ and $U$, we can only compensate for changes in the sign. Therefore, we have the following potential ambiguities.

$$
\begin{align*}
& \Phi_{B}^{\prime}=\Phi_{B} \\
& \Phi_{B}^{\prime}=\Phi_{B}-\pi / 2 \\
& \Phi_{B}^{\prime}=\Phi_{B}+\pi / 2 \\
& \Phi_{B}^{\prime}=\Phi_{B}+\pi \tag{A.7}
\end{align*}
$$

We have to compute the value of $\Theta_{B}^{\prime}$ that keeps the value of $Q$ and $U$ unchanged. Therefore, once we find a solution to the inversion problem in the form of the pair $\left(\theta_{B}, \phi_{B}\right)$, we can find the remaining solutions in the saturation regime following the recipes that we present now. Remember that, unless one knows the sign of $\cos \Theta_{B}$ (given by the observation of circular polarization), the number of potential ambiguous solutions is eight. If the polarity of the field is known, the number is typically reduced to four (or two if no $90^{\circ}$ ambiguity is present)

$$
\text { A.l } \Phi_{B}^{\prime}=\Phi_{B}
$$

Under this change, we have that

$$
\begin{align*}
\cos 2 \Phi_{B}^{\prime} & =\cos 2 \Phi_{B} \\
\sin 2 \Phi_{B}^{\prime} & =\sin 2 \Phi_{B} \\
\cos \Phi_{B}^{\prime} & =\cos \Phi_{B} \\
\sin \Phi_{B}^{\prime} & =\sin \Phi_{B} \tag{A.8}
\end{align*}
$$

Making use of the previous relations between the angles wrt to the vertical and the LOS, we have to solve the following equation.

$$
\begin{equation*}
\left(3 \cos ^{2} \theta_{B}^{\prime}-1\right) \sin ^{2} \Theta_{B}^{\prime}=\left(3 \cos ^{2} \theta_{B}-1\right) \sin ^{2} \Theta_{B} \tag{A.9}
\end{equation*}
$$

which can be written as

$$
\begin{align*}
& {\left[3\left(\cos \Theta_{B}^{\prime} \cos \theta-\sin \theta \sin \Theta_{B}^{\prime} \cos \Phi_{B}\right)^{2}-1\right] \sin ^{2} \Theta_{B}^{\prime} } \\
= & {\left[3\left(\cos \Theta_{B} \cos \theta-\sin \theta \sin \Theta_{B} \cos \Phi_{B}\right)^{2}\right.} \\
& -1] \sin ^{2} \Theta_{B} \tag{A.10}
\end{align*}
$$

After some algebra and doing the substitution $t=\sin \Theta_{B}^{\prime}$, we end up with the following equation to be solved.

$$
\begin{equation*}
A t^{4}+B t^{2}+C t^{3} \sqrt{1-t^{2}}=K \tag{A.11}
\end{equation*}
$$

where

$$
\begin{align*}
A= & -3 \cos ^{2} \theta+3 \sin ^{2} \theta \cos ^{2} \Phi_{B} \\
B= & 3 \cos ^{2} \theta-1 \\
C= & -6 \cos \theta \sin \theta \cos \Phi_{B} \\
K= & {\left[3\left(\cos \Theta_{B} \cos \theta-\sin \theta \sin \Theta_{B} \cos \Phi_{B}\right)^{2}\right.} \\
& -1] \sin ^{2} \Theta_{B} \tag{A.12}
\end{align*}
$$

The previous equation can be solved if we make the change of variables $t= \pm \sqrt{Z}$, resulting in

$$
\begin{align*}
& \left(C^{2}+A^{2}\right) Z^{4}+\left(-C^{2}+2 A B\right) Z^{3}+\left(-2 A K+B^{2}\right) Z^{2} \\
& \quad-2 B K Z+K^{2}=0 . \tag{A.13}
\end{align*}
$$

This polynomial of the fourth order can have four different solutions. From these solutions, we have to take only the real solutions which are larger than zero, given the range of variation of $\Theta_{B}$ :

$$
\begin{equation*}
t \in \mathbb{R}, \quad 0 \leqslant t \leqslant 1 \tag{A.14}
\end{equation*}
$$

Once the solutions for $t$ are found, we make $\Theta_{B}^{\prime}=\arcsin t$. Note that, for a fixed value of $t$, two values of $\Theta_{B}^{\prime}$ are possible. We choose the correct one by evaluating the expressions for $Q$ and $U$ and testing which of the two possible choices gives values equal (or very similar) to the original ones.

The angles $\left(\theta_{B}, \phi_{B}\right)$ are obtained by doing the transformation from $\left(\Theta_{B}^{\prime}, \Phi_{B}\right)$ to the vertical reference system

$$
A .2 \Phi_{B}^{\prime}=\Phi_{B}+\pi
$$

Under this change, we have

$$
\begin{align*}
\cos 2 \Phi_{B}^{\prime} & =\cos 2 \Phi_{B} \\
\sin 2 \Phi_{B}^{\prime} & =\sin 2 \Phi_{B} \\
\cos \Phi_{B}^{\prime} & =-\cos \Phi_{B} \\
\sin \Phi_{B}^{\prime} & =-\sin \Phi_{B} \tag{A.15}
\end{align*}
$$

Following the same approach, we have to solve for $\Theta_{B}^{\prime}$ in

$$
\left.\left.\begin{array}{l}
{\left[3\left(\cos \Theta_{B}^{\prime} \cos \theta+\sin \theta \sin \Theta_{B}^{\prime} \cos \Phi_{B}\right)^{2}\right.} \\
\quad-1] \sin ^{2} \Theta_{B}^{\prime} \\
=
\end{array}\right] 3\left(\cos \Theta_{B} \cos \theta-\sin \theta \sin \Theta_{B} \cos \Phi_{B}\right)^{2}\right) ~(-1] \sin ^{2} \Theta_{B} .
$$

The solutions are obtained as the roots of the same equations as before but now

$$
\begin{align*}
A= & -3 \cos ^{2} \theta+3 \sin ^{2} \theta \cos ^{2} \Phi_{B} \\
B= & 3 \cos ^{2} \theta-1 \\
C= & 6 \cos \theta \sin \theta \cos \Phi_{B} \\
K= & {\left[3\left(\cos \Theta_{B} \cos \theta-\sin \theta \sin \Theta_{B} \cos \Phi_{B}\right)^{2}\right.} \\
& -1] \sin ^{2} \Theta_{B} \tag{A.17}
\end{align*}
$$

The angles $\left(\theta_{B}, \phi_{B}\right)$ are obtained by doing the transformation from $\left(\Theta_{B}^{\prime}, \Phi_{B}+\pi\right)$ to the vertical reference system

$$
A .3 \Phi_{B}^{\prime}=\Phi_{B}+\pi / 2
$$

Under this change, we have

$$
\begin{align*}
\cos 2 \Phi_{B}^{\prime} & =-\cos 2 \Phi_{B} \\
\sin 2 \Phi_{B}^{\prime} & =-\sin 2 \Phi_{B} \\
\cos \Phi_{B}^{\prime} & =-\sin \Phi_{B} \\
\sin \Phi_{B}^{\prime} & =\cos \Phi_{B} . \tag{A.18}
\end{align*}
$$

Following the same approach, we have to solve for $\Theta_{B}^{\prime}$ in

$$
\begin{align*}
& {\left[3\left(\cos \Theta_{B}^{\prime} \cos \theta+\sin \theta \sin \Theta_{B}^{\prime} \sin \Phi_{B}\right)^{2}\right.} \\
&\quad-1] \sin ^{2} \Theta_{B}^{\prime} \\
&= 3\left(\cos \Theta_{B} \cos \theta-\sin \theta \sin \Theta_{B} \cos \Phi_{B}\right)^{2} \\
&-1] \sin ^{2} \Theta_{B} \tag{A.19}
\end{align*}
$$

The solutions are obtained as the roots of the same equations as before but now

$$
\begin{align*}
A= & -3 \cos ^{2} \theta+3 \sin ^{2} \theta \sin ^{2} \Phi_{B} \\
B= & 3 \cos ^{2} \theta-1 \\
C= & 6 \cos \theta \sin \theta \sin \Phi_{B} \\
K= & -\left[3\left(\cos \Theta_{B} \cos \theta-\sin \theta \sin \Theta_{B} \cos \Phi_{B}\right)^{2}\right. \\
& -1] \sin ^{2} \Theta_{B} . \tag{A.20}
\end{align*}
$$

The angles $\left(\theta_{B}, \phi_{B}\right)$ are obtained by doing the transformation from $\left(\Theta_{B}^{\prime}, \Phi_{B}+\pi / 2\right)$ to the vertical reference system

$$
A .4 \Phi_{B}^{\prime}=\Phi_{B}-\pi / 2
$$

Under this change, we have

$$
\begin{align*}
\cos 2 \Phi_{B}^{\prime} & =-\cos 2 \Phi_{B} \\
\sin 2 \Phi_{B}^{\prime} & =-\sin 2 \Phi_{B} \\
\cos \Phi_{B}^{\prime} & =\sin \Phi_{B} \\
\sin \Phi_{B}^{\prime} & =-\cos \Phi_{B} . \tag{A.21}
\end{align*}
$$

Following the same approach, we have to solve for $\Theta_{B}^{\prime}$ in

$$
\left.\left.\begin{array}{l}
{\left[3\left(\cos \Theta_{B}^{\prime} \cos \theta+\sin \theta \sin \Theta_{B}^{\prime} \sin \Phi_{B}\right)^{2}\right.} \\
\quad-1] \sin ^{2} \Theta_{B}^{\prime} \\
=
\end{array}\right] 3\left(\cos \Theta_{B} \cos \theta-\sin \theta \sin \Theta_{B} \cos \Phi_{B}\right)^{2}\right)
$$

The solutions are obtained as the roots of the same equations as before, but now

$$
\begin{align*}
A= & -3 \cos ^{2} \theta+3 \sin ^{2} \theta \sin ^{2} \Phi_{B} \\
B= & 3 \cos ^{2} \theta-1 \\
C= & -6 \cos \theta \sin \theta \sin \Phi_{B} \\
K= & -\left[3\left(\cos \Theta_{B} \cos \theta-\sin \theta \sin \Theta_{B} \cos \Phi_{B}\right)^{2}\right. \\
& -1] \sin ^{2} \Theta_{B} . \tag{A.23}
\end{align*}
$$

The angles $\left(\theta_{B}, \phi_{B}\right)$ are obtained by doing the transformation from $\left(\Theta_{B}{ }^{\prime}, \Phi_{B}-\pi / 2\right)$ to the vertical reference system.

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