COSMOLOGICAL SHOCKS IN ADAPTIVE MESH REFINEMENT SIMULATIONS AND THE ACCELERATION OF COSMIC RAYS

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ABSTRACT

We present new results characterizing cosmological shocks within adaptive mesh refinement *N*-body/hydrodynamic simulations that are used to predict nonthermal components of large-scale structure. This represents the first study of shocks using adaptive mesh refinement. We propose a modified algorithm for finding shocks from those used on unigrid simulations that reduces the shock frequency of low Mach number shocks by a factor of ~ 3 . We then apply our new technique to a large, $(512 h^{-1} \text{ Mpc})^3$, cosmological volume and study the shock Mach number (\mathcal{M}) distribution as a function of preshock temperature, density, and redshift. Because of the large volume of the simulation, we have superb statistics that result from having thousands of galaxy clusters. We find that the Mach number evolution can be interpreted as a method to visualize large-scale structure formation. Shocks with $\mathcal{M} < 5$ typically trace mergers and complex flows, while $5 < \mathcal{M} < 20$ and $\mathcal{M} > 20$ generally follow accretion onto filaments and galaxy clusters, respectively. By applying results from nonlinear diffusive shock acceleration models using the first-order Fermi process, we calculate the amount of kinetic energy that is converted into cosmic-ray protons. The acceleration of cosmic-ray protons is large enough that in order to use galaxy clusters as cosmological probes, the dynamic response of the gas to the cosmic rays must be included in future numerical simulations.

Subject headings: cosmic rays - cosmology: theory - hydrodynamics - methods: numerical

1. INTRODUCTION

What determines the thermal history of galaxy clusters? On large scales, it is governed by the infall of material onto dark matter halos and the conversion of gravitational potential energy into thermal energy. This process occurs through the heating of the gas via strong accretion shocks surrounding galaxy clusters and filaments (Ryu et al. 2003; Miniati et al. 2001b; Pfrommer et al. 2006; Pavlidou & Fields 2006). Once inside collapsed structures, complex flows associated with the merging of subhalos continue to create moderate-strength shocks that allow the halos to virialize. Because of this, shocks encode information about structure formation and its thermal effects on the gas.

Cosmological shocks affect three important realms of structure formation and leave feedback on the surrounding medium. First, shocks thermalize the incoming gas, providing much of the pressure support in baryons. This process is the basis on which clusters are able to virialize. In addition, the thermalization of gas at the standing accretion shocks surrounding large-scale filaments produces the warm-hot intercluster medium (WHIM) at temperatures of 10^5-10^7 K (Davé et al. 1999; Cen & Ostriker 1999). The history of the mass flux through these shocks describes the evolution of gas in the WHIM phase (Pfrommer et al. 2008).

Second, the strength of the outer accretion shocks onto halos, characterized by the Mach number, is dependent on the mass of the gravitating object. This is because the higher mass generates larger acceleration and velocity in the diffuse gas while the sound

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speed of the upstream gas is uniform for previously unshocked gas, corresponding to a temperature of $\approx 10^4$ K. This temperature floor is created by the reionization from stars. Thus, the Mach number of accretion shocks can be used as an independent measure of cluster mass. This could conceivably be a powerful new tool for cluster mass estimation if we are able to observe the accretion shock with radio observations (e.g., Giacintucci et al. 2008).

Finally, because these shocks are collisionless features whose interactions in the hot plasma are mediated by electromagnetic fields, it is possible for a portion of the thermal distribution of particles to be accelerated and transformed into nonthermal populations of cosmic rays (CRs) through the process of diffusive shock acceleration (DSA; e.g., Drury & Falle 1986; Blandford & Eichler 1987). This process results in a fraction of the kinetic energy of shocking gas being converted into both thermal and nonthermal components (Miniati 2001, 2007; Kang et al. 2002; Kang & Jones 2005, 2007). The CR electron populations are likely sources of radio halos and radio relics in galaxy clusters (Kim et al. 1989; Giovannini et al. 1993; Miniati et al. 2001a; Pfrommer et al. 2008), while the CR protons may be sources of γ -ray emission through their interactions with gas protons (Miniati 2002, 2003). If a significant portion of the gas pressure resides in CRs, then it will likely affect gas mass fraction estimates, as well as the assumption of hydrostatic equilibrium. Because of the importance of these mass estimates in measuring dark energy, we must include the underlying physics in order to perform precision cosmology (Allen et al. 2008).

To date, studies of cosmological shocks have included observational, theoretical, and numerical techniques. Observationally, the majority of the work surrounding cosmic shocks is related to radio relics, of which only a few have been studied in depth (e.g., Rottgering et al. 1997; Clarke & Ensslin 2006; Orrú et al. 2007). Using the spectral index of the nonthermal particle distribution, we can infer a Mach number if the acceleration is due to first-order Fermi acceleration (Giacintucci et al. 2008). In addition, *GLAST* will begin observing γ -rays and will likely see signatures

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from galaxy clusters due to hadronic CR interactions with pions (Pfrommer 2008).

On the theoretical side, the majority of analyses are based on manipulating the Press-Schechter formalism (Press & Schechter 1974; Sheth & Tormen 1999) to deduce first the mass function of accreting objects and then their interactions with infalling material. Pavlidou & Fields (2006) extended these analyses to calculate the energy and mass flux through accretion shocks. Furthermore, several analytical attempts have been made to describe merger shocks, including those by Fujita & Sarazin (2001) and Gabici & Blasi (2003a, 2003b). However, it is quite difficult to account for the complex morphologies that arise during structure formation using purely analytical frameworks. For this reason, multiple numerical techniques have been developed using hydrodynamical simulations.

There have been numerical studies of shocks using both Eulerian "single-grid" codes (e.g., Miniati et al. 2000; Ryu et al. 2003; Kang & Jones 2007), as well as smoothed particle hydrodynamics (SPH) codes (Pfrommer et al. 2006, 2007, 2008; Pfrommer 2008). There are advantages and disadvantages of both methods. In previous work using grid-based codes, shocks were analyzed during postprocessing by examining temperature jumps for a given point in time (Ryu et al. 2003). However, it was impossible to cover the spatial dynamic range needed to describe both the complex flow within halos and their coupling to large-scale structures because of the use of a uniform grid. Therefore, even the largest simulations, with 1024^3 cells in a $100 h^{-1}$ Mpc volume, have a comoving spatial resolution of only 97.7 h^{-1} kpc (Ryu et al. 2003). There have been recent attempts at prescribing hybrid models to study turbulent generation, but full-resolution convergence of the results has still not yet been achieved (Ryu et al. 2008). The advantage of a grid code is its superb shock-capturing algorithms that do not rely on the use of artificial viscosity when using higher order methods (O'Shea et al. 2005).

In contrast, SPH codes are implicitly adaptive in space due to the Lagrangian nature of the method; e.g., high-density regions are resolved by a larger number of particles than low-density regions. This approach conserves hydrodynamic quantities exactly when they are advected with the flow. However, because the properties of the gas are determined by a weighted average over neighboring particles, formally discontinuous shocks are spread over a length determined by the smoothing length. In addition, SPH relies on artificial viscosity to dissipate flows and produce the correct amount of entropy. Because of these restrictions, Pfrommer et al. (2006) developed a method that is able to identify shocks by examining the time evolution of the entropy of individual SPH particles. Comparing the instantaneous entropy injection rate to the characteristic time it takes a particle to cross the broadened shock surface, they are able to identify and calculate the instantaneous Mach number of shocks while remembering the preshock conditions. Therefore, the analysis can be performed on the fly, and shock quantities are traced along with the usual hydrodynamic properties. These calculations use calibrations against "shock tube" simulations to derive the correct relationship between entropy injection rate and Mach number, which may vary with respect to different artificial viscosity implementations.

To address all of the problems listed above, we have developed a novel numerical algorithm capable of detecting and identifying shocks in the three-dimensional adaptive mesh refinement (AMR) grid-based code Enzo. The use of AMR allows us to analyze unprecedented dynamic ranges with an advanced hydrodynamic code that is able to capture shocks exceedingly well. In this work we explore simulations with dynamic range of up to $2^{16} = 65,536$, but we are not prevented from going further in future work. Because of the complexity of the structure of AMR simulations, it was necessary to develop several new numerical algorithms to identify the shocks. This shock-finding analysis algorithm is presented and compared to previous methods (e.g., Ryu et al. 2003; Pfrommer et al. 2006). In order to validate and quantify the robustness of our method, we carry out a resolution study that includes both mass and spatial resolutions that vary by factors of 16 and 64, respectively.

We also propose a new method of characterizing shocks by their preshock overdensity and temperature. This then allows analysis that goes beyond the traditional internal versus external (of filaments/clusters) shock classification suggested by Ryu et al. (2003). By refining the temperature and density ranges examined, we are able to identify shocks that reside in voids, filaments, and halos. In addition, by using temperature cuts, we can identify the population of gas that is being shocked into the WHIM.

After calculating the shock structure in a given simulation, we are able to compute the amount of shock kinetic energy that is transferred to high-energy CR protons through DSA. While the surface area of the large-scale structure shocks is dominated by low preshock temperature and density, the bulk of the CR energy generation occurs in the centers of collapsed structures. Since stronger shocks will produce harder spectra (Blandford & Eichler 1987), we expect that the strong accretion shocks could be the source of high-energy CRs.

In § 2 we describe the numerical methods used for both the cosmological simulations and the analysis of the shock-finding process. In § 3 we compare our algorithm to that of Ryu et al. (2003) and test it using three-dimensional "shock tube" tests. Section 4 contains the main results of analyzing a large, $(512 h^{-1} \text{ Mpc})^3$, cosmological simulation with a peak spatial resolution of 7.8 h^{-1} kpc. Section 5 describes the effects of spatial and mass resolution on the shock populations and CR acceleration. In § 6 we discuss the limitations of our analysis, and in § 7 we summarize our findings and discuss potential future directions.

2. METHODOLOGY

2.1. The Enzo Code

All simulations were run using the Enzo cosmology code (Bryan & Norman 1997a, 1997b; Norman & Bryan 1999; O'Shea et al. 2004). While a full description can be found in the cited papers, we review the key aspects that are of importance to this work.

Enzo is a block-structured AMR (Berger & Colella 1989) code that couples an Eulerian hydrodynamics method that follows the gas dynamics with an *N*-body particle mesh (PM) solver (Efstathiou et al. 1985; Hockney & Eastwood 1988) to follow the dark matter component. Enzo implements two hydrodynamic solvers. The first is a piecewise parabolic method (PPM; Woodward & Colella 1984) with cosmological modifications by Bryan et al. (1995). The second is the method from the ZEUS magnetohydrodynamics code (Stone & Norman 1992a, 1992b). In this work we restrict ourselves to the PPM method because of its superior shock-capturing ability and lack of artificial viscosity.

The AMR scheme within Enzo is handled by partitioning the simulation volume into three-dimensional rectangular solid grids. Each of these grids contains a number of grid cells that set the spatial scale on which the hydrodynamics is solved. If a region of cells within a grid is determined to require higher resolution, as judged by a number of refinement criteria including gas/dark matter overdensity; minimum resolution of the Jeans length; local gradients of density, pressure, or energy; shocks; or cooling time, then a minimum enclosing volume around those cells is created at the appropriate level of refinement. These newly created "child

grids" can then themselves recursively become "parent grids" to yet another more highly refined region. This recursive nature does not set any restrictions on the number of grids or level of refinement. However, because structure formation leads to an enormous dynamic range, we are limited by available computational resources, and a maximum level of refinement l_{max} is instituted.

In addition to being adaptive in space, Enzo implements an adaptive time-stepping algorithm. All grids on a given level are advanced simultaneously with a maximum time step such that the Courant condition is satisfied by all the cells on that level. This results in a hierarchy of time steps: a parent grid on level l is advanced $\Delta t(l)$, and then its subgrid(s) on level l + 1 are advanced by one or more time steps until they reach the same physical time as their parent grid. At this point, flux information is transferred from child to parent grid in order to provide a more accurate solution to the hydrodynamics on the parent grid. This procedure is done recursively until all grids are at the same physical time as the root grid, at which point the process is repeated until the stopping point of the calculation is reached.

2.2. Shock-finding Algorithm

The bulk of our analysis relies on accurately identifying and quantifying the strength of shocks. After finding a shock, we would like to calculate its Mach number, which characterizes the strength of the shock. There are several methods that can be used in order to calculate the Mach number, including density, temperature, velocity, or entropy jumps across the shock. As in Ryu et al. (2003), we use the Rankine-Hugoniot temperature jump conditions to calculate the Mach number. The temperature jump is preferable to density because it is more sensitive to Mach number, whereas the density jump quickly asymptotes for strong shocks. The Mach number is solved for by

$$\frac{T_2}{T_1} = \frac{(5\mathcal{M}^2 - 1)(\mathcal{M}^2 + 3)}{16\mathcal{M}^2},\tag{1}$$

where T_2 and T_1 are the postshock (downstream) and preshock (upstream) temperatures, respectively, and M is the upstream Mach number.

A cell is determined to have a shock if it meets the following requirements:

$$\nabla \cdot \boldsymbol{v} < 0, \tag{2}$$

$$\nabla T \cdot \nabla S > 0, \tag{3}$$

$$T_2 > T_1, \tag{4}$$

$$\rho_2 > \rho_1, \tag{5}$$

where v is the velocity field, T is the temperature, ρ is the density, and $S = T/\rho^{\gamma-1}$ is the entropy. In our analysis, as in Ryu et al. (2003), we have set a minimum preshock temperature of $T = 10^4$ K, since the low-density gas in our cosmological simulations is assumed to be ionized (a reasonable assumption at $z \le 6$). Therefore, any time the preshock temperature is lower than 10^4 K, the Mach number is calculated from the ratio of the postshock temperature to 10^4 K. This introduction of a temperature floor prevents us from drastically overestimating the accretion shock strength in adiabatic simulations. Future work will incorporate a self-consistent UV ionizing background radiation.

Now the task is to identify all of the shocks and their corresponding Mach numbers. The method that has been previously used in unigrid simulations (e.g., Ryu et al. 2003) is to loop through rows of cells along each of the coordinate axes and identify one-dimensional shock structures in each direction. Contiguous cells that meet the requirements in equations (2)-(5) are then combined into a single shock structure, with the cell of maximum convergence marked at the center. The preshock and postshock cells are identified as the first cells outside of the shock structure. If a center is marked in more than one direction, the maximum calculated Mach number of the three possible is taken to be the true Mach number. Because of this, we would expect errors to arise when examining shocks whose direction of motion is not oriented along a coordinate axis. To address this issue, we have designed an algorithm that does not suffer from this limitation.

In our method, we first determine the direction of shock propagation from the local temperature gradients, making the assumption that the shock-induced temperature gradient overwhelms the background temperature gradient. We then search the cells along the temperature gradient for the preshock and postshock cells. If we find that a neighboring cell has a more convergent flow, that cell is marked as the center, and we move outward from it. This guarantees that the analysis is anchored to the center of the shock. Once the furthest preshock and postshock cells are found, the temperatures are taken, and the Mach number is calculated from equation (1). A two-dimensional analog of this process is shown in Figure 1. Because our algorithm is not confined to operating along the coordinate axes, the calculated Mach numbers provide a more accurate description of the underlying shock properties than the Ryu et al. (2003) method.

Specifically, in situations where there are weak shocks or complex flow velocities, using the coordinate-split approach may allow for an excess of shocks, since the direction of the shock wave is not taken into account. Our method picks a single direction in which a shock could be propagating, given a specific temperature gradient. Ryu et al. (2003) claim that their shocks are spread out over two to three cells, of which one is marked as the center. The coordinate-split approach may misidentify the other one to two cells as low Mach number shocks due to normal temperature gradients. This would lead to an overprediction of low Mach number shocks.

This process is further complicated by the use of AMR, primarily because neighboring cells are not necessarily at the same level of refinement. This occurs most often at the site of accretion shocks onto halos and filaments where the density gradient, on which the refinement criteria are based, is largest. Therefore, knowledge of the grid hierarchy must be used. We incorporate this into our algorithm and allow for a neighboring cell to be any cell at the same or lower level of refinement. We do not allow the algorithm to search for neighbors at higher levels (smaller grid cells), since one cell will have multiple neighbors. If this situation occurs, we use the neighboring cell on the same level. Because of this requirement, we must perform our analysis on the most highly refined grids first and move to progressively coarser levels of resolution.

2.3. Cosmic-Ray Acceleration Models

Following the method proposed in Ryu et al. (2003), we now seek to determine the amount of kinetic energy that is converted into heating the gas and accelerating CRs. We begin with calculating the total kinetic energy flux through a shock surface. The kinetic energy flux associated with a mass flux of $\rho_1 \mathcal{M}c_s$ is

$$f_{\rm KE} = \frac{1}{2} \rho_1 (\mathcal{M}c_s)^3, \tag{6}$$

where ρ_1 is the preshock density and c_s is the sound speed in the preshock gas. From this total incoming kinetic energy flux, a



Fig. 1.— Two-dimensional cartoon of our shock analysis algorithm. The shock centers are shown as dark blue cells, while the preshock and postshock cells are outlined in thick black. The AMR resolution level is seen by varying grid cell sizes.

fraction is used in the thermalization of the gas and the acceleration of CRs. In keeping with Ryu et al. (2003), we denote the amount of energy per unit time used to heat the gas and accelerate CRs as f_{TE} and f_{CR} , respectively. In the case of a purely hydrodynamical shock without the inclusion of CR feedback, the fractional thermalization $\delta_0(\mathcal{M})$ can be determined by the Rankine-Hugoniot jump conditions,

$$\delta_0(\mathcal{M}) = \frac{\left[e_{\text{TE},2} - e_{\text{TE},1}(\rho_2/\rho_1)^{\gamma}\right]v_2}{(1/2)\rho_1 v_1^3},\tag{7}$$

where $e_{\text{TE},1}$ and $e_{\text{TE},2}$ are the thermal energy densities in the preshock and postshock regions, respectively.

With the inclusion of CRs, there is no simple analytical form for the fractional thermalization of the gas, which depends on magnetic field orientation, turbulence, and the preshock CR population. Instead, we adopt the results of one-dimensional DSA simulations by Kang & Jones (2007). The time-asymptotic values of the fractional thermalization, $\delta(\mathcal{M}) = f_{\text{TE}}/f_{\text{KE}}$, and fractional CR acceleration, $\eta(\mathcal{M}) = f_{\text{CR}}/f_{\text{KE}}$, were found to be nearly self-similar for the temperatures and shock velocities considered. These simulations also accounted for whether or not the preshock medium had preexisting CRs. With a preexisting CR population, the fractional energy deposited into CRs increases dramatically at low Mach numbers because it is much easier to accelerate an existing power-law distribution of particles than a thermal distribution of particles. Shown in Figure 2 are the results of the Kang & Jones DSA simulations for a population with no preexisting CRs and one in which CRs existed initially with $P_{CR}/P_g \approx$ 0.3, where P_{CR} and P_g are the CR and total gas pressure, respectively. The sum of $\delta(\mathcal{M})$, $\eta(\mathcal{M})$, and the remaining fraction of kinetic energy in the gas is equal to 1, conserving energy.

We do not track the CR population in our simulations at present, and as a result we are unable to constrain the amount of preexisting CRs in the preshock medium. Therefore, we can think of our results from the two scenarios shown in Figure 2 as bracketing the likely range of efficiencies. In addition, these efficiency models are only valid for situations where the shock normal is parallel to the magnetic field. Any deviation from these ideal conditions will likely reduce the efficiency of CR acceleration (Kang & Jones 2007), so one can view the results described later in this paper as upper limits on CR injection efficiency.

2.4. Simulations

We constructed three distinct sets of cosmological simulations for this project. A summary of some of the simulation parameters



FIG. 2.—Fractional efficiency of gas thermalization and CR acceleration from the models by Kang & Jones (2007). Here $\delta_0(\mathcal{M})$ is the gas thermalization fraction expected from the Rankine-Hugoniot jump conditions, and $\delta(\mathcal{M})$ and $\eta(\mathcal{M})$ are the gas thermalization fraction and CR acceleration fraction, respectively, from the nonlinear calculations of Kang & Jones (2007). The two panels show results assuming different compositions of the preshock plasma. *Top*: Thermal gas with no CR population. *Bottom*: Thermal gas with a preexisting CR population with $P_{\rm CR}/P_g = 0.3$, where $P_{\rm CR}$ and P_g are the CR and total gas pressure, respectively.

is given in Table 1. First, we have a simulation that was devised as an analog of the unigrid numerical simulation by Ryu et al. (2003). For this simulation, we used cosmological parameters identical to those of Ryu et al. (2003) in order to provide a reference simulation to compare our new shock-finding method with previous work. The cosmological parameters for this simulation, ryu1024, are as follows: $\Omega_{BM} = 0.043$, $\Omega_{DM} = 0.227$, $\Omega_{\Lambda} = 0.73$, $h = H_0/(100 \text{ km s}^{-1} \text{ Mpc}^{-1}) = 0.7$, and $\sigma_8 = 0.8$, which are broadly consistent with *WMAP* year 5 results (Komatsu et al. 2008). The comoving size of the simulation volume is $(100 \ h^{-1} \ \text{Mpc})^3$ and is discretized into 1024^3 cells, giving a comoving spatial resolution of 97.7 h^{-1} kpc. It also employs 512^3 dark matter particles with a 1024^3 grid. In order to reproduce the Ryu et al. results as closely possible, we did not use AMR techniques. The simulation was initialized with an Eisenstein & Hu (1999) power spectrum with a spectral index of n = 1.0 at z = 99, and the simulation states were output 20 times between z = 10 and 0. The analysis of this simulation is described in § 3.2.

Our main results in this work focus on the analysis of a $(512 \ h^{-1} \ \text{Mpc})^3$ volume that utilizes a 512^3 root grid and up to seven levels of AMR. It is referred to as the "Santa Fe Light Cone" and has been previously described by Hallman et al. (2007). This simulation has a peak spatial resolution of 7.8 h^{-1} kpc and a dynamic range of 65,536. The cosmological parameters used are $\Omega_M = 0.3$, $\Omega_{\text{BM}} = 0.04$, $\Omega_{\text{CDM}} = 0.26$, $\Omega_{\Lambda} = 0.7$, $h = H_0/(100 \text{ km s}^{-1} \text{ Mpc}^{-1}) = 0.7$, and $\sigma_8 = 0.9$, and it employs an Eisenstein & Hu (1999) power spectrum with a spectral index n = 1.0. Cells are refined whenever the baryon or dark matter density increases by a factor of 8 beyond the previous level. Because the simulation then refines by a factor of 8 in volume, the average mass per grid cell stays roughly constant. The simulation is initialized at z = 99 and run to z = 0. The analysis of this simulation is described in § 4.

In order to study the effects of spatial and dark matter mass resolution, we have performed a suite of simulations that vary these factors, and we illustrate their results in § 5. These simulations are known as "nested grid" simulations. An initial cosmological simulation is run at low resolution. The most massive halo at z = 0 is found, and the simulation is recentered at the final location. The simulation is then rerun while only adaptively refining a region that bounds all dark matter particles that eventually are inside the most massive halo. Therefore, the focus of the simulation is only on the inner portion of the initial volume. With this capability, we are able to modify the root grid and peak spatial resolution for this subvolume and study their direct effects on the evolution of a single cluster. In our simulations, we initialize a $(256 h^{-1} \text{ Mpc})^3$ volume with 256^3 root grid cells. From that, we only adaptively refine in a $(32 h^{-1} \text{ Mpc})^3$ subvolume. Within the subvolume, we add up to two static nested grids with more highly refined dark matter particles and gas cells. A list of all simulation parameters used is given in Table 1. The cosmological parameters used are as follows: $\Omega_M = 0.268$, $\Omega_{BM} = 0.0441$,

TABLE 1 Simulation Parameters

Name	$L_{\rm box}$	$\Delta x_{\rm RG}$	l _{max}	$M_{ m dm}$	$\Delta x_{\rm max}$	Ω_b	Ω_m	σ_8
ryu1024	100	97.7	0	$5.877 imes 10^7$	97.7	0.043	0.27	0.8
Santa Fe Light Cone	512	1	7	7.228×10^{10}	7.8	0.04	0.3	0.9
m1_18	256	1	8	$6.224 imes10^{10}$	3.9	0.0441	0.268	0.9
m1_16	256	1	6	6.224×10^{10}	15.6	0.0441	0.268	0.9
m1_l4	256	1	4	$6.224 imes10^{10}$	62.4	0.0441	0.268	0.9
m4_18	256	500	8	7.781×10^9	3.9	0.0441	0.268	0.9
m4_16	256	500	6	7.781×10^{9}	15.6	0.0441	0.268	0.9
m4_l4	256	500	4	7.781×10^9	62.4	0.0441	0.268	0.9
m16_18	256	250	8	9.726×10^{8}	3.9	0.0441	0.268	0.9
m16_l6	256	250	6	9.726×10^{8}	15.6	0.0441	0.268	0.9
m16_l4	256	250	4	9.726×10^{8}	62.4	0.0441	0.268	0.9

Notes.—Here L_{box} is the simulation box size in comoving h^{-1} Mpc, Δx_{RG} is the effective root grid resolution (the m4 and m16 series of calculations use one and two static nested grids, respectively), l_{max} is the maximum level of AMR allowed in the simulation, M_{dm} is the dark matter particle mass (in the static nested grids for the m4 and m16 series of runs) in $h^{-1} M_{\odot}$, Δx_{max} is the peak spatial resolution in comoving h^{-1} kpc, Ω_b and Ω_m are the fractional densities of baryons and matter compared to the critical density ($\Omega_{\Lambda} \equiv 1 - \Omega_m$ in all simulations, so $\Omega_0 = 1$), and σ_8 is the power spectrum normalization of the mass fluctuation in a comoving 8 Mpc sphere.



FIG. 3.—Distributions of the ratio of calculated Mach number to expected Mach number from off-axis three-dimensional AMR shock tube test problems. Shock surface area, *S*, distributions were averaged over all orientations for each individual Mach number and normalized so that the area under the curve is 1. Lines correspond to Mach numbers of 2 (*dash-dotted*), 5 (*dashed*), 30 (*dotted*), and 100 (*solid*). Sample standard deviations from 1.0 are all less than 0.06.

 $\Omega_{\text{CDM}} = 0.2239, \,\Omega_{\Lambda} = 0.732, \, h = H_0/(100 \text{ km s}^{-1} \text{ Mpc}^{-1}) = 0.704, \text{ and } \sigma_8 = 0.9.$ These parameters are the *WMAP* year 3 parameters (Spergel et al. 2003) but with a somewhat higher σ_8 .

3. VALIDATION OF SHOCK-FINDING METHOD

3.1. Shock Tube Test

In order to verify that our shock-finding algorithm is accurate, we have performed a suite of three-dimensional AMR shock tube tests. In these tests we have varied the Mach number, as well as orientation, with respect to the coordinate axis. The setup of this test problem is described in Mihalas & Weibel Mihalas (1984). It consists of a stationary, uniform preshock medium. The shock is then introduced via boundary conditions that match the Rankine-Hugoniot jump conditions for a given Mach number. The volume is then allowed to adaptively refine up to two levels, using shocks as a criteria for refinement. We have chosen to adaptively refine based on shock locations (i.e., strong pressure jumps) instead of density because this should introduce a complicated AMR topology in order to test the robustness of our algorithm. This forces us to traverse different levels of refinement for preshock and postshock quantities.

In order to change the direction of shock propagation, we alter the time at which a given boundary cell switches from uniform to "shocked." Using this procedure, we vary the shock propagation vector over both θ and ϕ , which are angles off of the *x*-*z* and *x*-*y* planes, respectively. In addition to the three on-axis scenarios, we vary θ and ϕ over all permutations of the angles 0, $\pi/8$, $\pi/6$, and $\pi/4$. For each shock propagation direction, we then vary the input Mach number over $\mathcal{M} = 2, 5, 30$, and 100.

The general result from this study is that our shock-finding algorithm is very accurate. As shown in Figure 3, if we make a histogram of the ratio of calculated Mach number to expected Mach number and normalize it so that the area under the curve is equal to 1, the result is both accurate and precise. In Figure 3 we created the histogram by summing over all orientations of the shock of a given Mach number. As we can see, the peak is centered around 1.0, with an average sample standard deviation of less than 0.06. We have examined the average Mach number and standard deviation as a function of angle and found no discernible trend or bias.

In addition, due to the manner in which we set up the propagating shock, small inhomogeneities arise that are likely the cause of much of the calculated scatter. This is because we introduce the shock from the boundary conditions which do not explicitly keep the leading edge of the shock as a perfect discontinuity. Therefore, the accuracy of our shock-finding algorithm is likely better than that shown in Figure 3.

3.2. Comparison to Ryu et al. (2003)

In order to test our analysis against previous work done by Ryu et al. (2003), we generated a 1024^3 fixed grid simulation with cosmological parameters and spatial resolution identical to those of their most highly resolved calculation. This simulation is described in detail in § 2.4. We expect to see a difference in results from the shock-finding method and from underlying differences in the hydrodynamical solvers. Enzo uses the PPM, which captures shocks across a single zone, whereas Ryu et al. (2003) use the total variation diminishing (TVD) method, which spreads shocks over approximately two cells.

In order to study the differences between our shock-finding methods and those of Ryu et al. (2003), we mimic the top half of Figure 5 from Ryu et al. (2003) in our Figure 4. However, in addition to using our new shock-finding algorithm that searches along temperature gradients, we include a coordinate-split analvsis that is similar to that of Ryu et al. (2003). As we claimed in § 2.2, using a coordinate-split approach overpredicts the number of low Mach number and internal shocks. For external, low Mach number shocks, the difference is roughly a factor of 3, which agrees with our hypothesis that the coordinate-split approach identifies cells that are associated with a strong shock as the center of a weak shock. The difference in the internal shocks spans all Mach numbers because the flow is very complex, making it easy to mistake a normal temperature gradient for that of a shock. We have also studied the integrated kinetic flux through shock surfaces and find it to be in general agreement with Ryu et al. (2003). We will study this in more detail in the future when we include this analysis "on the fly."

While the shock surface area distributions are good indicators of qualitative differences, we now quantify these results. This is done by recreating Table 1 from Ryu et al. (2003) in our Table 2. For this portion of the analysis, we mimic the Mach number floor requirement that M > 1.5, which was used to reduce the effects of the complex flow in the Ryu et al. (2003) analysis. First, it is instructive to give a physical motivation for these parameters. The quantity 1/S can be thought of as a mean separation of shocks because it is the simulation volume divided by the total shock surface area. This gives it units of comoving Mpc. The ratio of external and internal shocks gives the reader an idea of where the majority of the shocks are occurring. Note that as the redshift decreases, the relative amount of internal shocks increases, indicative of the increase in shocks within halos and the measured amount of matter in large halos. The average quantities are surface area-weighted means of the quantity in question. A subscript of "ext" or "int" denotes that only external or internal shocks are used, respectively. External shocks are those with preshock temperatures less than 10⁴ K, while internal shocks are those with preshock temperatures greater than 10^4 K.



Fig. 4.—Differential shock surface area normalized by the comoving volume of the simulation for external (*left*) and internal (*right*) shocks for z = 0 in the ryu1024 simulation. The two methods of shock finding, coordinate split (*dotted line*) and coordinate unsplit (*solid line*), are shown. At low Mach numbers for external shocks and for all internal shocks we see a significant overprediction in the number of shocks when using the coordinate split method described in Ryu et al. (2003).

In comparing our Table 2 to Table 1 in Ryu et al. (2003), we find that we predict a higher average Mach number and higher mean comoving distances between shocks for both internal and external shocks. The ratio between our average external Mach number and that found in Ryu et al. ranges between 1.54 and 1.6, while that of the internal Mach number (disregarding z = 2.0) ranges between 1.3 and 1.5. We have disregarded z = 2.0 because there is a large amount of merging between z = 2.0 and 1.75, significantly raising the internal temperature of many of the large clusters, increasing the sound speed, and decreasing the Mach number. Therefore, we believe that our particular realization of this volume had later mergers than that of Ryu et al. (2003).

The differences in the average Mach numbers, as well as the increase in mean comoving distance between shocks, is almost entirely due to the use of a coordinate split algorithm versus a coordinate unsplit algorithm. The identification of many more low Mach number shocks increases the frequency, thus decreasing the comoving length between shocks. Therefore, for future studies, this difference must be taken into account.

	TABL	.E 2
Mean	Shock	QUANTITIES

Ζ	1/S	$S_{\rm ext}/S_{\rm int}$	$\langle M_{\rm ext} \rangle$	$\langle M_{\rm int} \rangle$	$1/S_{\text{ext}}$	$1/S_{int}$
0.0	6.235	3.550	12.65	3.767	7.992	28.37
0.25	6.519	4.312	13.02	3.961	8.030	34.63
0.50	6.886	5.196	12.86	4.119	8.211	42.67
0.75	7.301	6.248	12.61	4.225	8.470	52.92
1.0	7.767	7.442	12.26	4.310	8.811	65.57
1.25	8.297	8.743	11.81	4.399	9.246	80.84
1.50	8.884	10.18	11.34	4.412	9.756	99.38
1.75	9.546	11.59	10.89	4.411	10.37	120.2
2.0	10.31	13.04	10.50	7.679	11.10	144.8

Notes.—Mean shock quantities. Here z is the redshift of the simulation, 1/S is the mean comoving length between shock surfaces in units of h^{-1} Mpc, $S_{\text{ext}}/S_{\text{int}}$ is the ratio of shock surface area for external to internal shocks, and $\langle M_{\text{ext}} \rangle$ and $\langle M_{\text{int}} \rangle$ are the surface area—weighted mean of the external and internal shock Mach number, respectively. Also, $1/S_{\text{ext}}$ and $1/S_{\text{int}}$ are the average comoving distance between external and internal shocks, respectively, in h^{-1} Mpc.

4. RESULTS FOR THE SANTA FE LIGHT CONE VOLUME

Now that we have outlined our improved shock-finding algorithm, we apply it to a large cosmological simulation encompassing a volume of $(512 h^{-1} \text{ Mpc})^3$. This simulation, called the "Santa Fe Light Cone," was described previously by Hallman et al. (2007). This represents the first time that a large cosmological volume with superb spatial resolution has been studied for its shock and CR properties. Whereas previous studies were only able to study a small number (~10) of clusters due to a small cosmological box (Pfrommer et al. 2006), we have over 9000 halos with $M_{halo} > 5 \times 10^{13} M_{\odot}$ and over 200 with $M_{halo} > 5 \times 10^{14} M_{\odot}$. This allows us to perform a statistical study of cosmological shocks unlike any that has been done previously. Both the increase in volume (by a factor of ~125) and an enhanced spatial resolution over previous unigrid/SPH simulations allow unprecedented detail in our calculations.

We begin by outlining the shock distribution and how it can be thought of as a new way to view large-scale structure formation in the universe. We do this by breaking the distributions down by temperature and density cuts, which further illuminates the underlying dynamics. From there, we apply the DSA CR acceleration model and determine what phase of gas will contribute most to the acceleration of CRs. Finally, we estimate the global fraction of kinetic energy that is processed through shocks that is devoted to the acceleration of CRs in an effort to determine their possible dynamical effects on gas behavior in galaxy clusters.

4.1. Shock Frequencies

As was done in Ryu et al. (2003), we calculate the surface area of all shocks in a given logarithmic Mach number interval. However, instead of only classifying shocks as internal or external depending on their preshock temperature, we break the distribution into logarithmic temperature and density cuts that can be postprocessed to examine any subset of the ρ or T phase space for the entire computational volume. Primarily, we create several physically motivated temperature and density cuts, which are outlined in Table 3. Note that the gas in the $T < 10^4$ K heading is artificial, since we do not include a UV background. This temperature range traces gas that has not been previously shock-heated.

	TABLE 3	
,	FEMPERATURE-DENSITY PHASE SPACE	
		_

Location	Temperature Range (K)	Overdensity Range		
Voids	$T < 10^4$	$\delta < 1$		
Filaments	$10^4 < T < 10^6$	$1 < \delta < 100$		
Clusters	$10^{6} < T < 10^{8}$ $T > 10^{8}$	$100 < \delta < 10^3$ $\delta > 10^3$		
	- /	.,		

Note.—Approximate ranges for preshock temperature T or preshock overdensity $\delta = \rho_b / \langle \rho_b \rangle$ for general large-scale structures.

In addition to studying the physical properties of the preshock region, we study the evolution of the distributions as a function of redshift.

Figure 5 shows a projection of the Mach number for the largest cluster in the simulation $(2.8 \times 10^{15} M_{\odot})$ weighted by CR acceleration rate. This allows us to see the structure of cosmological shocks. By weighting the projection by CR acceleration rate, we see both the external high Mach number shocks and the internal shocks, since the internal shocks' weights are higher. In the other

three panels, we show the injected CR flux, density, and massweighted temperature.

4.1.1. Density and Temperature Ranges

We now expand the classification of external and internal shocks (Ryu et al. 2003) by examining the shock Mach number distributions in varying temperature and density ranges. This will provide a more complete description of where these shocks arise in structure formation than in previously published analyses. In Figure 6, the shock frequency is plotted for a range of density and temperature cuts. At z = 3, we see that shock surface area distribution is dominated by shocks with low-temperature/ low-overdensity preshock quantities. These represent the accretion shocks onto filaments and protoclusters. As the simulation evolves, the distribution becomes bimodal, with components from both low preshock temperature, low Mach number accretion shocks and high-temperature, low Mach number merger shocks.

The temperature cuts each have a characteristic Mach number cutoff that increases with decreasing temperature. This cutoff is due to the maximum temperature jump that is possible with a given preshock temperature. Therefore, since the maximum temperature



FIG. 5.—Projections of a $2.8 \times 10^{15} h^{-1} M_{\odot}$ cluster from the Santa Fe Light Cone. The Mach number (*top left*) is weighted by the injected CR flux. The injected CR flux (*top right*) is in units of ergs (s h^{-2} Mpc⁻²)⁻¹. The baryon column density (*bottom left*) is in units of $M_{\odot}(h^{-2}$ Mpc²)⁻¹. The mass-weighted temperature (*bottom right*) is in units of K. The total size of the projected volume is ($32 h^{-1}$ Mpc)³. All panels show logarithmic quantities.



FIG. 6.—Differential shock surface area as a function of logarithmic Mach number bins for varying preshock gas phases. Preshock gas overdensity (*top*) is divided into several ranges that differentiate the overall distribution. Preshock gas temperature (*bottom*) differentiates the different types of shocks (i.e., accretion and merger). Both distributions are shown for three redshifts: z = 3 (*left*), z = 1.5 (*middle*), and z = 0 (*right*).

in the simulation is $\sim 10^8$ K (determined by the mass of the largest cluster), a temperature jump from 10^6 K will result in $\mathcal{M} \approx 18$, very close to the cutoff seen at z = 0 for 10^6 K $< T < 10^7$ K. Similarly, the cutoffs for lower preshock temperatures indicate the largest temperature jumps for each population. At higher redshifts, these temperature cutoffs decrease due to the lower maximum temperatures present in the simulation. Therefore, the movement of these cutoffs tells us about the temperature evolution of the simulation.

In addition, the Mach number associated with the peaks in the shock frequency distribution can be used to determine the mathematical mode of the postshock temperature distribution. For z = 0, these peaks correspond to postshock regions with $T_2 \sim$ few × 10⁶ K for preshock temperatures $T_1 < 10^6$ K. Therefore, the majority of these shocks heat the preshock gas to WHIM temperatures in filaments. For $T_1 > 10^6$ K, the peak Mach numbers correspond to postshock temperatures of $T_2 \approx 2 \times 10^7$ to 1.5×10^8 K. These are complex flow and subhalo merger shocks in the interior regions of clusters.

If we instead examine the varying density cuts, similar results are observed. At high redshifts, we see that the dominating accretion shocks (high Mach number shocks) have preshock overdensities of $\delta \sim 1-10$. This is because of the relative paucity of large-scale halos and filaments and, thus, relatively shallow gravitational potential wells. The infalling gas will get much closer to the accretor and therefore denser before shocking. As we move to lower redshifts, the $\delta < 1$ shocks begin to dominate because we are shocking further out into the voids.

For the interior cluster shocks, there are three regimes that present themselves in the analysis. If we examine z = 3 with $10 < \delta < 100$, there are plateaus near $\mathcal{M} \approx 2-4$ and 10-70. It is difficult to determine what the postshock density will be because of the insensitivity of the density contrast at high Mach numbers ($\rho_2/\rho_1 \rightarrow 4$ for $\mathcal{M} \gg 3$). However, it is likely that the two high Mach number shock plateaus correspond to filaments for $\mathcal{M} \approx 10$ and clusters at the virial radius for $\mathcal{M} \approx 70$. The low Mach number shocks are most likely interior flow shocks.

At late times, all of the intermediate preshock density regions have bimodal distributions. The high Mach peak corresponds to density contrasts of 4, while the low \mathcal{M} corresponds to jumps of ~2. Therefore, we are likely looking at merger and complex flow shocks, respectively.

4.1.2. Redshift Evolution of Shock Properties

There are three primary populations of shocks that we see evolve through time, as seen in Figure 7. There are accretion shocks onto clusters, accretion shocks onto filaments, and merger and complex flow shocks within clusters and filaments. These are outlined in blue, green, and red in Figure 7, and their qualitative behavior can give useful insights as to the evolution of large-scale structure. Let us analyze each of these populations separately. To determine the origin of these populations, we have examined slices and projections of the data and compared the Mach number of the cell to its location with respect to large-scale structure.

First, at early times we see a small peak at very high Mach numbers that denotes accretion shocks onto collapsing halos. This corresponds to gas that has previously been untouched by shocks falling directly onto the protocluster gas, with temperature jumps from hundreds of K to 10^6 K (note that the Mach numbers are still calculated with a temperature floor of 10^4 K). We see that as the universe evolves, the strongest shocks in the simulation become stronger. This is due to the mass of the clusters increasing with time, providing a larger gravitational force pulling the material onto the halo. We also see that this peak increases in shock frequency while slowly moving to slightly lower Mach numbers. Because the mass function cuts off exponentially at high mass, the number of small halos heavily outweighs the number of large halos. These smaller halos have lower free-fall



FIG. 7.—Comoving shock surface area normalized by the simulation volume as a function of Mach number with varying redshifts. Three regions are suggested, corresponding to internal cluster merger shocks (*red*), accretion shocks onto filaments (*green*), and accretion shocks onto clusters (*blue*).

speeds at the radius of the accretion shock, leading to a smaller Mach number. Therefore, the large number of weaker shocks dominates the net surface area distribution.

Second, the shocks onto filaments begin at Mach numbers of $\mathcal{M} \sim 6$ and move toward $\mathcal{M} \sim 20$ at late times. The surface area of these shocks is much larger at early times because the surface area of a cylinder per unit volume is larger than that of a sphere, and there is an increased number of filaments with respect to halos (there are several filaments that feed into a single halo). The strength of these shocks grows with the increase in size of the filaments.

Finally, the low Mach number shocks (M < 3) due to halo mergers and complex flow are nearly nonexistent at high redshifts. However, as large halos collapse and start to merge, the shock surface area also increases. Therefore, this evolution traces the strength and frequency of merger shocks.

4.2. Cosmic-Ray Energy Injection

The thermal history of large-scale structure in the universe is primarily determined by the conversion of gravitational potential energy into kinetic energy, which is subsequently converted to heating gas and the acceleration of CRs. Here we present the results of our application of the CR acceleration model described in § 2.3 to the Santa Fe Light Cone.

4.2.1. Function of Redshift

The first result is that, as in previous studies (e.g., Ryu et al. 2003; Pfrommer et al. 2006; Kang et al. 2007), the most important Mach number shocks in terms of CR acceleration are at $\mathcal{M} \approx 2-4$. This may seem surprising, given that the surface area of shocks is dominated by high-Mach shocks. However, the amount of energy dissipation is the product of the mass flux through the shocks and the Mach number. The large accretion shocks at early times (z < 3) have already consumed a large fraction of the gas in voids. This leaves very little mass at low densities to be processed by the most massive halos. This is in contrast to the low-Mach



FIG. 8.—Redshift evolution of the amount of kinetic energy processed by shocks as a function of Mach number. Redshift decreases from z = 3 (*red line*) to z = 0 (*black line*). The decrease in flux at late times for M > 10 signals the epoch at which dark energy becomes dominant.

complex flow shocks within the clusters. These process very large amounts of mass and kinetic energy and therefore experience very high thermalization and acceleration of CRs even with lower efficiency. CRs from these low Mach number shocks will, however, have a steep energy spectrum and dissipate their energy relatively quickly compared to strong accretion shocks (e.g., Miniati et al. 2001b).

Figure 8 shows a distribution function of the kinetic energy processed through shocks per comoving $(h^{-1} \text{ Mpc})^3$ as a function of redshift where the height of the distribution function gives the differential amount of kinetic energy processed by shocks for a given Mach number bin. As the simulation evolves to z = 0.5, there is a monotonic increase in the average kinetic energy density processed. Both the low-Mach complex flow and high-Mach accretion shocks increase by factors of 10-100. This monotonic increase stops at $z \sim 0.5$ because of the dominance of dark energy in a Λ CDM universe at this epoch, resulting in a decreased merger of, and accretion shocks characterized by high Mach numbers will decrease. Compounding this effect is the slow evacuation of the voids and the lack of additional mass to accrete.

By applying the DSA model, we can estimate how much of this energy is put into gas thermalization versus the acceleration of CRs within the confines of the model. This acts as a first estimate of the energy injection into CRs and should not be taken as the final word on the subject. CR injection is a highly nonlinear process that is not fully understood. Further work on this model is needed.

Figure 9 shows the relative amounts of energy dissipated for the two different models involving either no preexisting CRs or an initial amount of CRs such that $P_{CR}/P_g \approx 0.3$. As one can see, the relative amount of CR acceleration versus thermalization heavily depends on the assumed inputs of the underlying DSA model. Until we are able to track the CR pressure within our simulations, we are resigned to giving these rough limits of CR acceleration.



FIG. 9.—Out of the incoming total kinetic energy of the shocks (*solid line*), the relative amount of energy devoted to the acceleration of CRs for models with (*dashed line*) and without (*dotted line*) a preexisting CR population, as predicted by the Kang & Jones (2007) DSA model.

4.2.2. Variation of Cosmic-Ray Injection Efficiencies with Gas Properties

Separation of distribution functions showing thermalization as a function of both temperature and density provides valuable insight into the physical processes occurring in the simulation. In Figure 10, we see that there are two primary modes of kinetic energy flux at z = 3. For $\mathcal{M} < 2$, the thermalization is dominated by shocks at $100 \le \delta \le 10^4$ and $T \ge 10^6$ K. These shocks are likely within the largest filaments and the first clusters. At higher Mach numbers, $\mathcal{M} > 6-7$, the thermalization is dominated by gas at $T < 10^6$ K and $\delta \sim 10-100$. This points toward accretion shocks onto filaments and the heating of the WHIM. If we use the peaks in each temperature cut up to $T \sim 10^6$ K to estimate the Mach number, we can calculate the postshock temperature for these shocks to be $(1-3) \times 10^6$ K. This reinforces the thought that these shocks are heating the WHIM. Shocks in this range of Mach numbers are also seen in Figure 5 as surrounding the filaments.

At later times, the entire distribution shifts to higher thermalization rates due to the collapse of structures. Low Mach numbers are again dominated by complex flows within clusters. By examining the shocks with preshock temperatures of less than 10^5 K, as well as the redshift evolution from Figure 8, we are able to verify that the high Mach number accretion shocks are becoming less important due to the separation of the voids from the clusters after $z \approx 0.5$. In the overdensity cut that corresponds to $1 < \delta < 10$, we see a shift from a peak at high Mach numbers to small Mach numbers as the relative importance of accretion and mergers switches.

If we compare our results to those of Pfrommer et al. (2006), we see a good agreement at low Mach numbers. Pfrommer et al. (2006) found shocks as strong as $\mathcal{M} \sim 10^3$. However, we never see shocks above $\mathcal{M} \approx 200$. This is likely due to the lack of a temperature floor in their simulation, which thus allows a higher numerical value for the Mach number. These shocks are likely not realized in the real universe due to the presence of a ubiquitous ionizing radiation background that will keep gas above 10^4 K.

Finally, we can compare our results to recent work by Kang et al. (2007), who used a unigrid calculation similar to that of Ryu et al. (2003) but included radiative processes, star formation, and a relaxed minimum temperature floor. Again, this relaxation of the temperature floor to (in their case) the CMB temperature resulted



FIG. 10.—Differential kinetic energy flux processed by shocks as a function of Mach number and preshock gas phase. Preshock gas overdensity (*top*) is divided into several ranges that differentiate the overall distribution. Each preshock temperature range (*bottom*) roughly corresponds to a particular Mach number. Both distributions are shown for three redshifts of z = 3 (*left*), z = 1.5 (*middle*), and z = 0 (*right*).



FIG. 11.—Effects of spatial resolution in different density regimes. Here we keep the mass resolution at the highest level $(M_{\rm dm} = 9.7 \times 10^8 \ M_{\odot})$. The distribution function of shock Mach numbers in a $(32 \ h^{-1} \ {\rm Mpc})^3$ volume around a cluster weighted by surface area for three overdensity cuts is plotted against Mach number. Three cuts in overdensity are shown for $\delta < 100$ (*black lines*), $100 < \delta < 10^4$ (*blue lines*), and $\delta > 10^4$ (*red lines*). Varying spatial resolutions are shown with dotted (62.4 $\ h^{-1}$ kpc), dashed (15.6 $\ h^{-1}$ kpc), and solid (3.9 $\ h^{-1}$ kpc) lines.

in very high Mach numbers, up to $M > 10^4$. This corresponds to a temperature jump by a factor of $\sim 3 \times 10^7$, a jump from 3 to 10^8 K (the minimum and maximum temperatures in the simulation). At low Mach numbers, our results are very similar to those of Kang & Jones (2007).

5. EFFECT OF MASS AND SPATIAL RESOLUTION ON COSMIC-RAY ACCELERATION EFFICIENCY

In order to quantify the robustness of our simulations with respect to mass and spatial resolution, we perform a series of simulations where the mass and spatial resolution of a single galaxy cluster are varied over a wide range of parameter space. Two parameters are varied in this study. The first is the maximum level of refinement, which affects the spatial resolution and, ultimately, the accuracy of the hydrodynamic solver. The second parameter is the dark matter particle mass resolution, which affects the accuracy with which the gravitational potential is calculated.

5.1. Spatial Resolution

Our maximum spatial resolution ranges from $62.4 h^{-1}$ kpc to $3.9 h^{-1}$ kpc (see Table 1). Since this only limits the maximum resolution, one expects to see a strong dependence on this parameter only at high densities. Figure 11 shows the dependence of shock surface area on level refinement for three overdensities. For shocks with preshock overdensities less than ~100, the main difference in the multiple resolutions is at low Mach numbers (below $\mathcal{M} \sim 2$) and only appears in the lowest resolution simulation.

At overdensities above 10^3 , we not only see that the low Mach number complex flow shocks are lost at low resolution, but we also see a drop in the number of high Mach number shocks. At this density and spatial refinement, it is thought that the absence of sufficient spatial resolution leads to the artificial smoothing of the gas, creating an inability to capture shocks. The main result of this spatial resolution study is that a resolution between $3.9 h^{-1}$ kpc and $15.6 h^{-1}$ kpc should be sufficient in all but the most dense regions of the simulations. Therefore, our Santa Fe Light Cone simulation presented in § 3 had an adequate peak resolution of 7.8 h^{-1} kpc.



FIG. 12.—Spatial resolution effects on kinetic energy flux for several density regimes. The kinetic energy flux is plotted against Mach number for varying spatial resolutions denoted by different lines. The shocks are grouped as external (*black lines*), clusters/filaments (*blue lines*), and rich clusters (*red lines*).

To examine the effect of spatial resolution on CR acceleration, we study the kinetic energy flux through shocks as a function of spatial resolution. Figure 12 shows a distribution function measuring the thermal dissipation rate as a function of Mach number with varying spatial resolution. This study is performed with the maximum mass resolution, $M_{\rm dm} = 9.7 \times 10^8 \ M_{\odot}$. At low overdensities ($\delta < 100$), the effect of spatial resolution is very small. At moderate to high overdensities ($100 < \delta < 10^4$), there are differences on the order of a factor of 2 that are likely due to the smoothing of high-density gas as the resolution is decreased. The primary difference in the dissipation rates occur for low Mach numbers when we do not have sufficient spatial resolution to resolve all of the complex flow shocks. There are also large differences at $\mathcal{M} \geq 10$ for the lowest resolution simulation. However, the difference between $3.9 \ h^{-1}$ kpc and $15.6 \ h^{-1}$ kpc is negligible.

At very high overdensities ($\delta > 10^4$), there is a very large difference between the varying spatial resolutions. One reason is that if a cell has an overdensity of 10^4 , the grid will normally be on the fifth level of refinement. With a maximum refinement level of 4 for the poorest resolution simulation, any gas at this overdensity will be very poorly resolved. The difference between the 15.6 h^{-1} kpc and 3.9 h^{-1} kpc resolution simulations is likely small number statistics for the former simulation. The 3.9 h^{-1} kpc resolution simulation will resolve these high densities with roughly 64 times more cells compared to the 15.6 h^{-1} kpc simulation.

5.2. Mass Resolution

The mass resolution of each simulation is set by the resolution of the root grid (or highest level static nested grid). The size of each root cell determines the amount of mass given to each dark matter particle. Therefore, if the root grid doubles in resolution, the mass resolution increases by a factor of 2^3 . In principle, there should be two effects of increased mass resolution. First, one would expect that since we are extending our mass function to a lower limit, the number of subhalos and our resolution of complex fluid flow should increase. This should manifest itself in an increase in shocks in the low Mach number regime. Second, the increased mass resolution. This may affect the calculated surface area of shocks that reside in voids. Since the temperature jumps in the voids are likely to be much higher than those within clusters, we would expect this effect to show up in the high Mach number regime.



FIG. 13.—Effects of mass resolution in different density regimes. Here we keep the spatial resolution at the highest level of $3.9 h^{-1}$ kpc. Mass resolutions are shown by dotted lines ($6.2 \times 10^{10} M_{\odot}$), dashed lines ($7.8 \times 10^9 M_{\odot}$), and solid lines ($9.7 \times 10^8 M_{\odot}$). The shocks are grouped as external (*black lines*), clusters/ filaments (*blue lines*), and rich clusters (*red lines*).

In order to test these hypotheses, we varied the mass resolution from $6.2 \times 10^{10} h^{-1} M_{\odot}$ to $9.7 \times 10^8 h^{-1} M_{\odot}$. The results of this study are shown in Figure 13. At $\delta < 100$, we see that as the mass resolution increases, the number of low Mach number shocks increases, while the high Mach number shocks decrease. At high densities, the situation is more complicated. For $\mathcal{M} < 2$, the surface area likely increases because of the increase in the number of subhalos and complex flow. For M > 7-8, the differences seem to be largely due to statistical uncertainties. For $\delta > 10^4$, the disparity at $\mathcal{M} < 2$ is again likely due to the number of subhalos and their effects on turbulence. At 2 < M < 5, there is a large difference between the highest mass resolution simulation and the other two. Because there are just too few dense subhalos that merge with large halos to create this surface area.

As with the spatial resolution, we now study the effects of mass resolution on the thermal dissipation rates at shock fronts. Figure 14 shows the effect of varied mass resolutions with a fixed spatial resolution of $3.9 h^{-1}$ kpc. Again, we break the analysis down into overdensity regimes. Low-overdensity, high Mach number shocks exhibit a strong dependence on mass resolution. This is because of the ability to better resolve shocks in the voids and low-density filaments. The disparity in high-overdensity ($100 < \delta < 10^4$), low Mach number shocks is less apparent but also suggests that the mass resolution of the simulation has an effect on the thermal dissipation of gas through shocks. At $\delta > 10^4$, we again see the effect of a decreased number of subhalos available to merge.

Contrary to the effects of spatial resolution, the biggest differences due to mass resolution appear in the high Mach number regime. This is again due to the overestimate of the Mach number at low root grid resolution. One evident result is that while the spatial resolution seems to be fairly well converged, it is not clear that the mass resolution has converged. Therefore, we can only claim a fairly weak precision in the thermal dissipation and CR acceleration rates for the current simulations.

There are several key results to this resolution study. We appear to have converged in terms of maximum spatial resolution in all but the densest cluster gas. However, our convergence on the various quantities with respect to dark matter mass resolution is not clear. The differences in the CR acceleration rate are not larger than the underlying uncertainty in the results of DSA sim-



FIG. 14.—Spatial resolution effects on kinetic energy flux for varying dark matter particle masses. Mass resolutions are shown by dotted lines $(6.2 \times 10^{10} M_{\odot})$, dashed lines $(7.8 \times 10^9 M_{\odot})$, and solid lines $(9.7 \times 10^8 M_{\odot})$. The shocks are grouped as external (*black lines*), clusters/filaments (*blue lines*), and rich clusters (*red lines*).

ulations, suggesting that both mass resolution and our understanding of the physical mechanisms of CR acceleration must be improved in the future.

6. DISCUSSION

There are several topics that warrant discussion with respect to the results that we have presented thus far. These include the variation of results with respect to σ_8 , the inclusion of nonadiabatic physics, the limitation of the DSA model, and the implications of the mass resolution in the Santa Fe Light Cone simulation.

If our goal is to do large statistical studies of galaxy clusters, changing the value of σ_8 will have significant effects. First, a higher σ_8 will greatly increase the number of massive clusters in a given volume. By comparing the ryu1024 simulation with the Santa Fe Light Cone, with values of σ_8 of 0.8 and 0.9, respectively, we see that this increases the frequency and strength of the high Mach number shocks. In addition, this should increase the amount of kinetic energy that is processed by shocks, since mergers will be more frequent.

In all of our simulations thus far we have only used adiabatic physics. Previous studies, such as those done by Kang et al. (2007), have found when including radiative cooling and star formation that the shock properties are still governed primarily by gravitational physics and that additional physics have little effect on overall distributions at scales larger than $\sim 100 \ h^{-1}$ kpc. However, Pfrommer et al. (2007) found that at smaller scales, on the inside of clusters, the CR contribution to the overall pressure is greatly increased with the inclusion of radiative cooling. In addition, we currently adopt a temperature floor of 10^4 K because of the lack of an ionizing background. This should instead be done in a self-consistent manner.

While we use the results of recent DSA simulations by Kang & Jones (2007), there are assumptions and limitations that may have an effect on our results. We assume that the magnetic field is parallel to the shock normal, which yields the largest efficiency for accelerating CRs. Any deviation from this will likely cause decreases in the overall efficiency of the shocks as particle accelerators. In addition, for low Mach numbers, knowledge of the preshock composition is very important and can lead to orders-of-magnitude differences in the acceleration efficiency. Therefore, being able to track the CR pressure in on-the-fly calculations will allow us to provide a more self-consistent estimate. Finally, we

assume that the only method for CR production is through firstorder Fermi acceleration, and therefore we ignore other potential sources of CRs, such as second-order acceleration by turbulence, galaxies, and AGNs.

The results of the resolution study provided in § 4 suggest that we have not yet seen a convergence with respect to the dark matter particle mass in the Santa Fe Light Cone simulation. This likely results in an underprediction in the number of merging subhalos and the kinetic energy flux associated with them.

7. CONCLUSIONS AND FUTURE DIRECTIONS

Our study of cosmological shocks has resulted in several advances in both scientific understanding and numerical algorithms. We summarize the key findings as follows:

1. We have developed a novel numerical scheme that is capable of detecting and accurately characterizing the Mach numbers of shocks in an adaptive mesh refinement (AMR) simulation. This method has relaxed the previous restriction of using a coordinated axis-based approach and now allows us to accurately characterize shocks that have any orientation with respect to the coordinate grid.

2. Using our new shock-finding technique on a unigrid cosmological simulation that is identical to the highest resolution calculation in Ryu et al. (2003), we have shown that previous methods resulted in an overestimate of the number of low Mach number shocks by a factor of \sim 3 due to confusion about the direction of shock propagation, and that this underestimate is consistent with using shock-finding algorithms that only sweep along coordinate axes.

3. We have analyzed the largest AMR cosmological simulation to date that includes adiabatic gas physics, the Santa Fe Light Cone. This simulation has an effective spatial dynamic range of 65,536 and resolves both large-scale structure and small-scale features within galaxy clusters. Whereas previous studies were able to study on the order of 10 high-mass clusters, we have thousands within a single simulation volume. Our study of this simulation has led to a new technique for conceptualizing structure formation because we are able to analyze the evolution of three different populations of shocks: cluster accretion, filament accretion, and internal merger and complex flow shocks.

4. By applying the results of one-dimensional diffusive shock acceleration models, we calculate the amount of kinetic energy at shock fronts that is used to accelerate cosmic rays, and we find it to be in agreement with previous studies. These cosmic rays

will make up a significant fraction of the total pressure in the intracluster medium, and therefore their dynamical effects need to be studied.

5. We have performed a resolution study that varies both the dark matter particle mass and peak spatial resolution. From the results of this study, we believe that the spatial refinement in the Santa Fe Light Cone simulation is adequate. The state of mass resolution convergence is less clear, suggesting that for future studies we should focus on higher mass resolution.

While our numerical technique of characterizing shocks has been proven to be robust, our results are still somewhat limited by the physics. We have not yet included potentially important effects such as radiative cooling, star formation and feedback, AGN heating, or a photoionizing UV background. These physics will be included in future work. Second, our results are based on postprocessing of the simulation output. Ideally, the shocks would be identified in an on-the-fly manner during simulation run time. In addition, the acceleration would be traced in a selfconsistent manner that allowed for a back-reaction on the gas. Attempts at tracing the cosmic-ray pressure have been made by Pfrommer et al. (2006, 2007) using an SPH code, and we will be working toward the same goal in the near future within Enzo. Finally, the acceleration of cosmic rays is still dependent on the underlying magnetic field strength and orientation. Cosmological MHD has been implemented within Enzo, and in the near future we will include magnetic fields and their coupling to cosmic rays within a cosmological AMR volume.

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