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Skin image illumination modeling and chromophore identification for melanoma diagnosis

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Abstract

The presence of illumination variation in dermatological images has a negative impact on the automatic detection and analysis of cutaneous lesions. This paper proposes a new illumination modeling and chromophore identification method to correct lighting variation in skin lesion images, as well as to extract melanin and hemoglobin concentrations of human skin, based on an adaptive bilateral decomposition and a weighted polynomial curve fitting, with the knowledge of a multi-layered skin model. Different from state-of-the-art approaches based on the Lambert law, the proposed method, considering both specular reflection and diffuse reflection of the skin, enables us to address highlight and strong shading effects usually existing in skin color images captured in an uncontrolled environment. The derived melanin and hemoglobin indices, directly relating to the pathological tissue conditions, tend to be less influenced by external imaging factors and are more efficient in describing pigmentation distributions. Experiments show that the proposed method gave better visual results and superior lesion segmentation, when compared to two other illumination correction algorithms, both designed specifically for dermatological images. For computer-aided diagnosis of melanoma, sensitivity achieves 85.52% when using our chromophore descriptors, which is 8–20% higher than those derived from other color descriptors. This demonstrates the benefit of the proposed method for automatic skin disease analysis.

Keywords: adaptive bilateral decomposition, weighted polynomial curve fitting, melanin identification, hemoglobin identification, skin disease analysis

(Some figures may appear in colour only in the online journal)
1. Introduction

Skin color is an important characteristic for accurate diagnosis and grading of cutaneous lesions by experienced dermatologists in clinical practice. For example, the presence of multiple color shades and pigmentation asymmetry within lesions often indicates a high risk of developing malignant melanoma (MM) (Friedman et al. 1985). However, the visual perception of skin color is not only credited to major chromophores (melanin and hemoglobin) underneath the skin surface, but is affected by external illumination and spectral responses of imaging detectors. Skin color representation in a specific color space (e.g. RGB and its transformations) is not a genuine physical quantity. It is derived from color matching functions of the human visual system (Wandell 1995). It sometimes fails to provide precise information about the concentrations of cutaneous chromophores, and is easily influenced by external imaging factors. For example, figure 1 shows an MM image, whose pigmentation information is partially concealed by illumination artifacts. As a result, conventional colorimetry may not properly describe the underlying histological content of skin and tends to yield less trustworthy results when colorimetry is applied directly to skin disease analysis.

A number of studies have been developed for the non-invasive assessment of melanin and hemoglobin on skin lesion images. Claridge et al. (2003) proposed a sophisticated multi-layered skin model based on the Kubelka-Munk theory for extracting epidermal and dermal melanin, blood, and collagen thickness using multispectral skin data. Yamamoto et al. (2008) applied a much simpler three-layered skin model based on the Lambert law, and calculated the melanin index and erythema index in RGB skin images. But Claridge’s approach requires multispectral images, which are not always available in clinical practice; while Yamamoto’s algorithm is reported to be sensitive to circumstantial imaging conditions, as there is no illumination-modeling step to correct external imaging factors. As a result, conventional colorimetry may not properly describe the underlying histological content of skin and tends to yield less trustworthy results when colorimetry is applied directly to skin disease analysis.

Tsumura et al. (2003) removed shading effects by a color vector analysis in the optical density domain, and applied independent component analysis (ICA) on RGB skin images to separate average concentrations of melanin and hemoglobin. Similarly, Madooei et al. (2012) introduced extra imaging factors (e.g. shading, sensor characteristics) to a diffuse reflection skin model and canceled out their influences by directly dividing two spectral responses in original lesion images. Then they applied the ICA approach on the post-processed RGB channels for extracting chromophore densities. These methods show efficiency for shading removal in skin color images, and their chromophore descriptors are useful for characterizing cutaneous pigmentation for MM diagnosis. However, the ICA-based methods are only responsible for separating a skin image into two independent components. They do not associate the knowledge of the absorbance spectrum. This results in ambiguities when differentiating melanin from hemoglobin.

All the above methods, which either specified (Tsumura et al. 2003, Madooei et al. 2012) or did not include (Claridge et al. 2003, Yamamoto et al. 2008) an illumination correction function, refer to human skin as a merely diffuse reflectance surface. They ignore the specular reflection at the air–skin interface. But this component is generally believed to be the cause of highlight and its effect changes with viewing direction. Accordingly, these existing methods will fail to address highlight effects in skin lesion images captured under non-polarized conditions.

This paper, considering human skin as a specular and diffuse reflectance model, proposes a novel illumination correction and chromophore identification scheme on dermatological images by following three steps. First, specular reflection is separated from diffuse reflection through specular pixel localization and a B-spline image interpolation. Second, the resulting diffuse image is decomposed into a base layer and a detail layer. The base layer, having
low-frequency illumination and shading effects, is approximated by polynomial curve fitting taking an initial illumination map from an adaptive bilateral filter as a priori. The detail layer, containing high-frequency chromophore reflectance, is calculated by subtracting the base layer from the diffuse spectral band in a logarithmic form. Finally, incorporating the knowledge of chromophore absorption characteristics, melanin density and hemoglobin density are well identified using detail layers from different spectral channels.

Experiments show that the proposed method is able to address highlight and strong shading effects in dermatological photographs of large dynamic range intensity. The derived chromophore descriptors, more efficient in describing pigmentation distributions of skin, demonstrate that they will be useful for improving the automatic diagnosis of melanoma.

2. A multi-layered skin model

Human skin can be simplified as a thin structure with distinctive multiple layers, which correspond to the melanin-rich epidermis, hemoglobin-rich dermis, and subcutis with collagen and fat (Tsumura et al. 2003). Based on this multi-layered model, previous methods (Tsumura et al. 2003, Madooei et al. 2012) used the Lambert law to characterize skin radiance provided that there is little specular reflection at the skin surface. This diffuse reflectance model is efficient in modeling skin images captured under polarized lighting (e.g. dermoscopy images), but it is hard to handle cutaneous images illuminated under uncontrolled imaging settings. Therefore, this study considers skin as a specular reflection and diffuse reflection model in figure 2, and skin image intensity \( I \) at pixel \((x, y)\) and wavelength \( \lambda \) can be written as a combination of specular reflection \( I_s \) and diffuse reflection \( I_d \) as:

\[
I(x, y) = I_s(x, y) + I_d(x, y)
\]

\[
= Q_s[k_s E_s(w_s(x, y))^{\alpha} + k_d E_d w_d(x, y)e^{-k_d \alpha}]
\]

where \( Q_s \) stands for sensor characteristics. \( k_s \) and \( k_d \) are the specular reflection constant and diffuse reflection constant, respectively. \( E_s \) and \( E_d \) are intensities of specular and diffuse components of light source. \( w_s \) is the specular factor giving rise to highlight, which is the dot product between viewer direction and specular reflection direction. \( \alpha \) is a material relevant constant, which assigns a large value for a smooth surface while a small value for a rough one. \( w_d \) is the wavelength-independent shading variable due to scene geometry, which...
The dot product between surface normal and lighting direction. \( \mu_{m,j} \) and \( \mu_{h,j} \) are wavelength-dependent absorptive coefficients of melanin and hemoglobin, respectively. \( l_{m,j} \) and \( l_{h,j} \) are the accumulated path lengths of photons in the epidermis and dermis layers. \( c_m \) and \( c_h \) are densities of melanin and hemoglobin in a sampled volume of skin.

3. Methods

3.1. Specular reflection and diffuse reflection separation

Yang et al (2010) estimate the maximum diffuse chromaticity of the specular pixels by applying bilateral filter to the maximum fraction of the color components in original image, such that the maximum diffuse chromaticity can be propagated from the diffuse pixels to the specular pixels. This method works well for removing specular reflection on images of man-made objects, which have smooth surfaces and distinctive hue colors. But it poses much difficulty when applied directly on texture-rich skin images. This is because human skin has areas sharing similar hue values but different saturations. Surface texture in these areas will be filtered out as the specular component. As a result, the diffuse image becomes blurred, and part of the skin texture information, having diagnostic importance, is lost. These drawbacks can be clearly detected in the diffuse image of an MM example derived from (Yang et al 2010) in figure 3(c).

In this study, we apply Yang’s method to localize candidate specular component first. Then the highlight areas are decided by selecting pixel intensity larger than a threshold, which is set to 0.25 times of the maximum intensity in candidate specular image. Compared to the candidate specular component (figure 3(a)), the surface texture is greatly reduced in the specular image after thresholding (figure 3(b)).

In principle, the diffuse reflection can be obtained by subtracting the specular component from original skin image. But direct subtraction may yield some fake intensity pixels, visible as dark spots, in the derived diffuse image (figure 3(c)). This is because the image intensity of these pixels is dominated by specular reflection, while diffuse reflection is largely missing due to local surface smoothness and observation direction. Subtraction results in small pixel intensity in all the RGB channels, but not the real diffuse chromaticity. This undesired effect becomes worse when specular reflection is strong.

To circumvent this problem, the diffuse chromaticity of the detected specular pixels is obtained by a B-spline interpolation (Thévenaz et al 2000) using neighboring non-specular points as:

![Figure 2. A three-layered skin reflectance model.](image-url)
where $M_s$ is a set of specular pixels after thresholding. $\Omega_{(x,y)} = \{(i,j)\}$ is the neighborhood of pixel $(x,y)$ where $|rx| = |x-i/4| < 2$, $|ry| = |y-j/4| < 2$. $W_{\Omega_{(x,y)}}$ is a matrix of $\Omega_{(x,y)}$ assigning 1 to non-specular pixels and 0 to specular pixels. $K_{rx}$ and $K_{ry}$ are vectors of interpolation coefficients in $x$- and $y$-directions. Figure 3(d) shows the diffuse reflection image derived from our method.

### 3.2. Decomposition of diffuse reflection image

After specular reflection removal, the remaining diffuse reflection can be formulated by a linear combination of chromophore coefficients, optical parameters of light source, and the effects of scene geometry in an inverse logarithmic form as,
3.2.1. Initial illumination approximation. Bilateral filter, first proposed in (Tomasi and Manduchi 1998), was developed for image denoising, meanwhile preserving important edges and features. It extends the concept of Gaussian smoothing through a weighted average process of neighboring pixels. In this study, bilateral filter is applied to diffuse skin image \( \log \frac{I_{\text{ed}}}{I_{\text{log}}} \) to estimate the initial illumination map. The output image \( \log \frac{I_{\text{ed}}}{I_{\text{log}}} \) after filtering at pixel \((x, y)\) and wavelength \(\lambda\) is given as:

\[
\log I'_{\text{d,\lambda}}(x, y) = \frac{1}{A} \sum_{(p, q) \in \Omega_{xy}} \varphi((p, q), (x, y)) \Phi(\log I_{\text{d,\lambda}}(p, q), \log I_{\text{d,\lambda}}(x, y)) \log I_{\text{d,\lambda}}(p, q) \\
= [-\log Q_{\lambda} - \log E_{\text{d,\lambda}}] \\
+ \left[ \frac{1}{A} \sum_{(p, q) \in \Omega_{xy}} \varphi((p, q), (x, y)) \Phi(\log I_{\text{d,\lambda}}(p, q), \log I_{\text{d,\lambda}}(x, y)) \\
(\mu_{m,\lambda} I_{m,\lambda}(p, q) + \mu_{h,\lambda} I_{h,\lambda}(p, q) - \log w_\lambda(p, q)) \right] \\
\]

(4)

where \((p, q)\) belongs to the neighborhood \(\Omega_{(x,y)}\) of pixel \((x, y)\), and \(A\) is a normalizing constant. The first term of the above equation refers to illumination information, which is a function of \(\lambda\). The second term contains chromophore reflectance \(\mu_{d,c}\) and shading effects \(w_\lambda\), whose contributions in \(\log I'_{\text{d,\lambda}}\) are controlled by a spatial function \(\varphi\) and a range function \(\Phi\), defined as Gaussian kernels in this study:

\[
\varphi((p, q), (x, y)) \Phi(\log I_{\text{d,\lambda}}(p, q), \log I_{\text{d,\lambda}}(x, y)) \\
= \exp\left(-\frac{\| (p, q) - (x, y) \|^2}{2\sigma_1^2}\right) \exp\left(-\frac{\| \log I_{\text{d,\lambda}}(p, q) - \log I_{\text{d,\lambda}}(x, y) \|^2}{2\sigma_2^2}\right) \\
\]

(5)

Considering that shading is normally a low-frequency component which changes gradually across large skin areas, high-frequency chromophore elements can be smoothed out by selecting relatively large spatial \(\sigma_1\) and intensity \(\sigma_2\) standard deviations (SD), whose values depend on specific applications. By subtracting \(\log I'_{\text{d,\lambda}}\) from \(\log I_{\text{d,\lambda}}\), intrinsic chromophore information can be obtained. We then embed this bilateral filtering in an iterative process such that chromophore reflectance will iteratively propagate till the difference between images before and after filtering is smaller than a threshold \(t\) for each pixel. In this study, \(t = 0.01 \times \log_2(255) \approx 0.05\), which means 1% of the overall image intensity range. The iterative process is summarized as Algorithm-1 below.

**Algorithm-1: Initial illumination approximation**

**Input:** \( I_{\text{loop}} = \log I_{\text{d,\lambda}} \)

**Repeat:** (1) Apply bilateral filter on \( I_{\text{loop}} \), store filtered image \( I'_{\text{loop}} \).

(2) Compute propagated chromophore reflectance \( I = I + I_{\text{loop}} - I'_{\text{loop}} \), and the remaining component after this iteration \( I_{\text{remain}} = \log I_{\text{d,\lambda}} - I \).

(3) If \( I_{\text{loop}} - I_{\text{loop}} < t \) for every pixel, step outside loop. Otherwise \( I_{\text{loop}} = I_{\text{remain}} \), and repeat steps (1)~(3).

**Output:** \( L_{\text{ini,\lambda}} = I_{\text{remain}} \)
It should be noted that the effectiveness of illumination approximation by standard bilateral filter depends on the selection of $\sigma_1$ and $\sigma_2$ for individual images. Large spatial and intensity SDs may make the normal skin areas overly smoothed, and part of the shading effects fail to be removed; while small SDs could lead to poor illumination estimation, where overall lesion areas appear as shading in the estimated illumination map. As a result, the contrast between lesion areas and surrounding normal skin was greatly reduced in the corrected image.

In order to cope with this problem, we take image intensity gradients as reference to make the spatial and range standard deviations adaptive to each pixel:

$$\sigma_{1,j}(x,y) = \min\left( R_{g_x}, R_{g_y} \right) * G_j(x,y), \sigma_{2,j}(x,y) = R_{g_{L,j}} * G_j(x,y)$$  \hspace{1cm} (6)

$$G_j(x,y) = 1 - \exp\left( -\frac{\left\| \nabla I_{L,j}(x,y) \right\|}{2\sigma_G^2} \right)$$  \hspace{1cm} (7)

where $R_{g_x}$ and $R_{g_y}$ are the width and height of the image, and $R_{g_{L,j}}$ is the maximum intensity value in the diffuse image of channel $j$. $G_j$ is a monotonically increasing function of image intensity gradient $\nabla I_{L,j}$, and $\sigma_G$ controls the increasing rate of function $G_j$. Hence, pixels of large intensity gradients, corresponding to lesion areas, are assigned large SDs; whereas pixels of small intensity gradients, referring to homogeneous normal skin, are given small $\sigma_1$ and $\sigma_2$ values (figure 4(d)). Using this adaptive bilateral filter, shading effect is kept in the filtered image; meanwhile chromophore components are gradually smoothed out during each iteration.

Figure 4(e) shows the illumination approximation of the MM example in figure 3, derived from Algorithm-1 applying the proposed adaptive bilateral filter. It is obvious that shading effects on the left are well preserved in the RGB channels due to the selection of small smoothing parameters, while most of the chromophore information is removed as high-frequency elements by a strong averaging process. But varied SDs at different pixels make the illumination estimation $L_{ini}$ unnatural and less homogeneous. Thus, a polynomial curve fitting is subsequently introduced to generate the final illumination image.

3.2.2. Final illumination modeling. Polynomial function $f$ in equation (8) is applied as a parametric modeling of lighting variation. Three sets of polynomial orders $(nx, ny) \in N$, corresponding to horizontal shading $(2,1)$, vertical shading $(1,2)$, and radial shading $(2,2)$, are considered in this study. Our objective is to optimize the polynomial coefficients $\rho$ in the model through minimizing the cost function (9) using the initial illumination estimation $L_{ini}$ as a priori.

$$f(x, y, nx, ny) = \begin{cases} \sum_{w=x}^{nx} \sum_{v=0}^{ny} \rho_{w,v} x^w y^v & nx \geq ny \\ \sum_{v=x}^{ny} \sum_{w=0}^{nx} \rho_{v,w} x^w y^v & nx < ny \end{cases}$$  \hspace{1cm} (8)

$$f = \arg\min_{(nx,ny) \in N} \left( \sum_{(x,y) \in I} \left\| L_{ini,j}(x,y) - f(x, y, nx, ny) \right\| \right)$$  \hspace{1cm} (9)

where $\omega_j$ is a monotonically decreasing function defined as $\omega_j = \beta^{\nabla I_{L,j}}$ with $\beta = 0.01$ as a constant. It assigns relatively smaller weights to pixels in skin lesion areas with a large intensity gradient, so that normal skin areas give greater contribution in calculating the final illumination map. As shown in figure 5, the introduction of weight $\omega_j$ enables the parameter $\sigma_G$ in equation (7) to be chosen in a larger range without greatly influencing the final illumination estimation. In this study, we set $\sigma_G = 0.3$ throughout the work.
Subtracting the final illumination estimation from the diffuse reflection component, a skin image can be decomposed into a base layer $I_{\text{base}}$ having low-frequency imaging factors, and a detail layer $I_{\text{detail}}$ containing chromophore reflectance:

$$I_{\text{base}}(x, y) = -\log_G Q_d - \log_G E_d(x, y) - \log_G w_d(x, y)$$

$$I_{\text{detail}}(x, y) = \mu_m L_{\text{base}} c_m(x, y) + \mu_h L_{\text{detail}} c_h(x, y)$$

We will take $I_{\text{base}}(x, y)$, $I_{\text{detail}}(x, y)$, $c_m(x, y)$, and $c_h(x, y)$, as $I_{\text{base}}$, $I_{\text{detail}}$, $c_m$, and $c_h$ for simplicity hereafter.

From figure 4, the resultant base layers, responsible for the low-frequency component across large smooth regions, match with the varied illumination information in the original spectral bands at different wavelengths. The corresponding detail layers show pigmentation in large skin regions with little illumination influence. In addition, it is worth noting that the exact degree of pigmentation in the detail layers greatly changes among the RGB channels.
This is because the absorbance spectrum of melanin and hemoglobin varies with wavelength. Thus, the diffuse reflectance of skin in a specific spectral band can be considered as an effect attributed to particular chromophores. Therefore, the melanin index and hemoglobin index can be calculated.

### 3.3. Melanin index and hemoglobin index estimation

As shown in figure 6, melanin, the major pigmentation chromophore, effectively absorbs light from 400 to 1,000 nm; whereas oxyhemoglobin and deoxyhemoglobin, the major blood chromophores, both greatly absorb light around 450 and 570 nm, respectively. Due to the increased spectrum attenuation of hemoglobin, the absorption at longer wavelength light (>620 nm) is dominated by melanin, whilst that of hemoglobin is negligible. Associating chromophore absorbance with the spectral responses of conventional RGB cameras, image intensity in the red channel (~650 nm) is primarily attributed to melanin concentration, while those of the green (~550 nm) and blue (~450 nm) channels are the joint simultaneous effects of melanin and hemoglobin. The detail layers of skin image intensity in the RGB channels can then be expressed as:

\[
I_{\text{detail},r} = \mu_{m,r}I_{\text{m},r} + \mu_{h,r}I_{\text{h},r}
\]

\[
I_{\text{detail},g} = \mu_{m,g}I_{\text{m},g} + \mu_{h,g}I_{\text{h},g}
\]

\[
I_{\text{detail},b} = \mu_{m,b}I_{\text{m},b} + \mu_{h,b}I_{\text{h},b}
\]
Based on the previous publications about absorptive coefficients and light penetration lengths into human skin (Jacques 1998, Keller et al 2001), the melanin density and hemoglobin density can be estimated:

\[
\begin{pmatrix}
    c_m \\
    c_h
\end{pmatrix} = \begin{pmatrix}
    \mu_{m,r}I_{m,r} & 0 \\
    \mu_{m,g}I_{m,g} & \mu_{h,g}I_{h,g} \\
    \mu_{m,b}I_{m,b} & \mu_{h,b}I_{h,b}
\end{pmatrix}^{-1} \begin{pmatrix}
    I_{\text{detail},r} \\
    I_{\text{detail},g} \\
    I_{\text{detail},b}
\end{pmatrix}
\]

\[
= \begin{pmatrix}
    0.4313 & -0.229 & 0.9456 \\
    -0.2349 & 0.8262 & -0.3451
\end{pmatrix} \begin{pmatrix}
    I_{\text{detail},r} \\
    I_{\text{detail},g} \\
    I_{\text{detail},b}
\end{pmatrix}
\]

(15)

In this study, the melanin index is defined as \( \text{MI} = c_m \) and the hemoglobin index is \( \text{HI} = c_h \). Figure 7 shows the MI and HI of the MM image in figure 3. This example has both dark brown/black (lesion) and reddish (vessels) responses, reflecting the underlying melanin and hemoglobin densities respectively. The MI mapping from our method successfully addresses the shading effects, giving apparent contrast between blackish areas within MM and surrounding healthy skin. The corresponding HI mapping has few highlight effects, and reveals the capillaries that are concealed by illumination in the ICA approach (Madooei et al 2012). All these should lead to more accurate results in automatic skin disease analysis.

4. Experiments and results

4.1. Experimental data and setup

For algorithm evaluation, a number of 258 conventional RGB skin lesion images, including 76 MMs, 182 benign nevi (BN), are collected from two public databases (Diepgen et al 2014,
Galderma 2014). Of these lesions, 154 were reported to be excised and examined by histopathology, giving 76 MMs and 78 BN diagnosed as 34 dysplastic nevi, 30 common acquired nevi, 8 blue nevi, 5 Spitz nevi, and 2 seborrheic keratosis. The remaining 104 lesions did not undergo excision biopsy due to no evidence of malignancy under clinical examination.

Automatic skin lesion segmentation and computer-aided melanoma diagnosis are performed to show the usefulness of the proposed method in skin disease analysis. In the lesion segmentation experiment, images after illumination modeling by our approach are first visually compared with the results from two other illumination correction methods (Cavalcanti and Scharcanski 2011, Glaister et al. 2013). Both were developed specifically for skin image analysis. Then automatic lesion segmentation is performed as quantitative analysis, taking manual segmentation by an experienced board-certificated dermatologist as reference.

In the melanoma classification experiment, diagnostic features are extracted from the resulting images after illumination modeling. These features are then forwarded to a linear support vector machine using a ten-fold cross validation as the training–testing strategy (Theodoridis and Koutroumbas 2006). Sensitivity (SE) and specificity (SP) are recorded to evaluate the classification performance for differentiating MM from BN. The area under the receiver operating characteristic curve (AUC) is calculated, with a confidence interval of 95%. Classification results, computed by diagnostic features extracted from images after different illumination modeling approaches, are compared to demonstrate the effectiveness of the algorithms.

Figure 7. Melanin and hemoglobin concentrations calculated by different algorithms. (a) MI and (b) HI derived from the proposed approach. (c) First and (d) second independent components by the ICA method (Madooei et al. 2012).
4.2. Lesion segmentation

Figure 8 shows six example skin lesion images after illumination correction by different methods. It is noted that the Cavalcanti and MSIM methods cause a color change in the shading areas, whilst the proposed method maintains a consistent chromaticity of healthy skin. This can be clearly observed in figures 8(b) and (d). Furthermore, for skin images having complex surface shapes and oversaturated illumination variations, such as figures 8(c) and (f), the Cavalcanti and MSIM methods fail to satisfactorily remove the shading effects, whilst the proposed method successfully addresses the undesired artifacts.

Based on results after illumination modeling, the skin images are segmented into lesion and non-lesion areas by the same Otsu’s method (Otsu 1979). Taking manual segmentation by the dermatologist as reference, the Tanimoto coefficient ($TC$) defined in equation (16) is adopted to quantitatively evaluate the segmentation performance (Tan et al 2005),

$$TC = \frac{\xi_{\text{manual-auto}}}{\xi_{\text{manual}} + \xi_{\text{auto}} - \xi_{\text{manual-auto}}} \times 100\% \tag{16}$$

where $\xi_{\text{manual-auto}}$ denotes the number of pixels assigned to lesion areas by both manual and automatic segmentations. $\xi_{\text{auto}}$ is the number of lesion pixels computed by the automatic
method, and \( \zeta_{\text{manual}} \) is that selected by the dermatologist. \( TC \) becomes 1 if automatic segmentation is exactly the same as the manual one, whilst it is 0 when there is no overlapping between them.

Table 1 shows the segmentation accuracy on uncorrected and corrected skin lesion images by different algorithms. It is noted that all the methods show efficiency for correcting illumination variations and improving lesion segmentation accuracy. But compared to the state-of-the-art algorithms under consideration, the proposed method proved superior as well as reliable in illumination modeling, which gives the highest average \( TC \) value and the lowest \( SD \) in the segmentation experiment.

### 4.3. Melanoma classification

In order to demonstrate the efficiency of the chromophore indices for skin disease analysis, the present study compares the computer-aided melanoma diagnosis using diagnostic features derived from RGB colorimetry and chromophore indices. Based on the widely applied ABCD rule (Friedman et al. 1985), the diagnostic features including absolute color variation, relative color variation (Sun et al. 2013), and global point signature-based asymmetry measures (Liu et al. 2012), are extracted from each skin lesion image using the existing computer-based analytical algorithms. For RGB colorimetry, these features are extracted from red, green, and blue channels as shown in equation (17). Whilst for chromophore indices, these features are extracted from MI and HI mappings in equation (18). The computed diagnostic features are normalized using a z-score transformation (Aksoy and Haralick 2001), so that 99% elements of each feature are in the range of 0–1 to prevent features of large ranges dominating the classification.

\[
F_{\text{RGB}} = \left\{ CV_{\text{les}}^R, CV_{\text{les}}^G, CV_{\text{les}}^B, CV_{\text{rel}}^R, CV_{\text{rel}}^G, CV_{\text{rel}}^B, \text{Asy}_{\text{min}}^R, \text{Asy}_{\text{min}}^G, \text{Asy}_{\text{min}}^B, \text{Asy}_{\text{min}}^{R+90}, \text{Asy}_{\text{min}}^{G+90}, \text{Asy}_{\text{min}}^{B+90} \right\}
\]

\[
F_{\text{chrom}} = \left\{ CV_{\text{les}}^\text{MI}, CV_{\text{les}}^\text{HI}, CV_{\text{rel}}^\text{MI}, CV_{\text{rel}}^\text{HI}, \text{Asy}_{\text{min}}^\text{MI}, \text{Asy}_{\text{min}}^\text{HI}, \text{Asy}_{\text{min}}^{\text{MI}+90}, \text{Asy}_{\text{min}}^{\text{HI}+90} \right\}
\]

For comparison, experiments based on RGB colorimetry refer to the classifications using descriptors from original uncorrected images and corrected images after illumination modeling by the Cavalcanti method, the MSIM method and the proposed method. While experiments based on chromophore indices are the classifications using descriptors from MI and HI mappings computed by the ICA method (Madooei et al. 2012) and our method. The corresponding melanoma classification results are summarized in table 2.

For classification in RGB colorimetry, our method greatly increased sensitivity by 4–8% and specificity by 8–21%, in comparison to the results derived from uncorrected and corrected images by the other methods. Moreover, the sensitivity of automatic melanoma diagnosis has been further improved 12% via applying the diagnostic descriptors from chromophore indices, with 5% sacrifice in specificity. Considering that the most important objective for
3428 melanoma diagnosis is to maximize the correct recognition rate of malignant lesions, the best classification is achieved by using the chromophore descriptors from the proposed method, which give 85.52% sensitivity, 84.07% specificity, and 84.50% overall diagnostic accuracy, respectively.

5. Discussion

5.1. Comparison of illumination modeling methods

In the present study, two other illumination-modeling approaches, Cavalcanti’s method and the MSIM method, are considered for performance comparison. It is noted that the Cavalcanti and MSIM approaches cannot address highlight effects in the lesion images, while the proposed method can successfully remove this artifact. This is because both the Cavalcanti and MSIM approaches refer to human skin as a merely diffuse reflectance surface, and ignore the specular reflectance in their skin models. But our method considers both specular and diffuse reflectance, so it is able to deal with highlight and shading effects in skin images of large dynamic range intensity. Hence, lesion image reported in figure 8(f), failed to be satisfactorily corrected due to highly oversaturated illumination variation (Glaister et al 2013), but was well modeled by the proposed method. Its corresponding lesion segmentation is close to the manual one outlined by the experienced dermatologist.

Furthermore, the Cavalcanti and MSIM methods make two assumptions about skin lesion images. First, skin lesion in the image is assumed to be illuminated by a single source of white light (Glaister et al 2013). Hence, only V-channel in the HSV color space is used for illumination correction. But this assumption is not always true for skin images from public databases. This is probably the reason why the Cavalcanti and MSIM methods sometimes cause a color change within the shading areas of healthy skin (figures 8(b) and (d)). Conversely, the proposed method does not make the above assumption and corrects the illumination variations in all the RGB channels. Hence, it maintains a consistent color across homogeneous healthy skin in the corrected lesion images.

Second, both the Cavalcanti and MSIM methods assume that skin lesion is found in the center of the photograph. Thus, they suppose healthy skin is near the corners and borders of the image. Accordingly, they use pixels in these areas to estimate the illumination map. These methods can remove shading effects when lighting variations in skin images are relatively simple (figures 8(a) and (e)). But limited pixel information poses much difficulty when characterizing skin lesion images having more complex illumination due to skin surface shapes and oversaturated variations (figures 8(c) and (f)). In comparison, our method properly

| Table 2. Melanoma classification results using diagnostic features extracted from RGB colorimetry and chromophore indices. |
|-----------------------------------------------|----------------|----------------|----------------|--------|
|                                               | SE (%)    | SP (%)    | Acc. (%)     | AUC    |
| RGB colorimetry Uncorrected                  | 65.78     | 68.67     | 67.83        | 0.649  |
| Cavalcanti (Cavalcanti and Scharcanski 2011) | 69.74     | 76.92     | 74.51        | 0.706  |
| MSIM (Glaister et al 2013)                   | 71.05     | 80.77     | 77.90        | 0.748  |
| Our method                                   | 73.68     | 89.56     | 84.88        | 0.867  |
| Chromophore indices ICA (Madooei et al 2012) | 77.63     | 78.57     | 78.29        | 0.759  |
| Our method                                   | **85.52** | **84.07** | **84.50**    | **0.870** |
describes the sophisticated lighting variations by using all the image pixels to estimate the illumination map. As a result, the proposed method gave visually superior corrected images and higher lesion segmentation accuracy in experiments. In addition, it is worth noting that the central localization assumption works only for single lesion images, such as MM diagnosis. But it is not applicable to skin images where several lesions exist, e.g. acne detection; while we proved in our earlier study that the proposed method works on this kind of skin image (Liu and Zerubia 2013).

5.2. Comparison of melanoma classification using RGB colorimetry and chromophore indices

For classification in RGB colorimetry, melanoma diagnostic accuracy, particularly specificity, greatly increases after illumination correction. This is because illumination modeling results in more accurate lesion segmentation and color feature quantification, allowing a better distribution separation between MM and BN.

Classifications using chromophore indices largely boost the sensitivity, thanks to the melanin index and hemoglobin index properly characterizing the pathological tissue conditions of the skin (Dolotov et al 2004). Take the melanoma image in figure 1 for example. The shape of this malignant lesion is more or less symmetric and its color variations are relatively small in the RGB color space. Hence, it was erroneously classified as a benign nevus in the diagnostic experiments using RGB colorimetry-based descriptors. In comparison, chromophore indices are physical measures. The irregular growth of melanin is generally believed to be the cause of malignant melanoma. Accordingly, measuring melanin distribution provides a way to evaluate the genetic instability underneath the skin surface. In this instance, pigmentation asymmetry and pigmentation variation of the lesion obviously increase in the melanin index mapping in figure 7. This leads to a correct classification using chromophore-based descriptors, which categorizes the lesion as a malignant case. Hence, compared to the RGB colorimetry, chromophore indices are more efficient in describing the pigmentation distribution of the cutaneous lesions, and therefore can benefit the automatic skin disease analysis.

5.3. Limitation

The method discussed in this article was implemented in Matlab R2012b (Natick, MA, USA) on a PC with an Intel i5-4460 CPU and 8GB DDR3-1600 RAM. Since the spatial (σ1) and intensity (σ2) standard deviations are adaptive to every pixel in bilateral filtering, the computation power for processing the algorithm cannot achieve real time. Take figure 1 with a spatial resolution of 740 × 488 pixels for example. It takes 183.86 s to remove highlight and shading effects under the platform stated above. If a compiled language such as C++ is used, the computational time can trivially be reduced by at least an order of magnitude. But in order to achieve real-time computation, one possible way could be to group pixels having similar intensity gradients and make them share the same spatial and intensity standard deviations during computation.

Another limitation lies in the fact that only one dermatologist’s/histopathologist’s evaluation was used to create the gold standard. As such, it is not possible to characterize inter-operator error. Although resources were not available in this study to allow for multiple experts to examine the images, in our opinion, the results still elucidate the efficiency of the proposed method for improving the quality of clinical data and assisting physicians to achieve better diagnostic results. Nevertheless, a future endeavor should strive to investigate whether the estimated error is on the order of the inter-operator error.
6. Conclusion

This paper proposes a novel illumination modeling and chromophore identification method in dermatological images for melanoma diagnosis. The derived melanin and hemoglobin indices are well identified, and prove robust to highlight and shading effects in skin color images captured under uncontrolled imaging settings. Experiments show that the proposed method gives superior visual and segmentation results when compared to two other illumination correction approaches. Chromophore descriptors greatly increase the sensitivity of automatic melanoma diagnosis rather than those derived from RGB colorimetry. We expect that this new method will prove useful for other skin disease analysis.

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